

# MEAN CURVATURE FLOW OF SPACELIKE GRAPHS

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I am going to talk about my recent joint work with Guanghan Li (arXiv:0804.0783;0801.3850).

We consider the product  $\Sigma_1 \times \Sigma_2$  of two Riemannian Manifolds  $(\Sigma_i, g_i)$  with the pseudo-Riemannian metric  $g_1 - g_2$ , and a map  $f : \Sigma_1 \rightarrow \Sigma_2$  defining a spacelike graph  $F(p) = (p, f(p))$ . We assume  $\Sigma_1$  is compact and  $\Sigma_2$  complete with bounded curvatures.

We consider the Mean Curvature Flow  $F_t$  for  $F_0 = F$ . Under certain conditions on the sectional curvatures  $K_i$  of  $\Sigma_i$ :  $K_1 \geq K_2^+$ , we prove the flow  $F_t$  remains a spacelike graph of a map  $f_t$  and exists for all time  $t$ , and if  $\Sigma_2$  is compact then for a sequence  $t_n \rightarrow +\infty$ ,  $F_{t_n}$  converges at infinity to a maximal graph.

Then we apply Bernstein-Calabi results obtained by L. Alias and A. Albuje (arXiv:0709.4363) for the case  $\dim(\Sigma_2) = 1$ , and extended by the authors (arXiv:0801.3850) to higher codimension  $\dim(\Sigma_2) = n$ , to conclude the limit is the graph of a totally geodesic map and is a slice if  $K_1 > 0$  somewhere.

If  $K_1 > 0$  everywhere we prove the mean curvature of  $F_t$  is exponentially decreasing on  $t$ , what allows to drop the compactness assumption and prove the convergence of all the flow to a unique slice.

We apply this result to prove that given any Riemannian manifolds  $\Sigma_1, \Sigma_2$ , with  $K_1 > 0$ , for any map  $f : \Sigma_1 \rightarrow \Sigma_2$  with  $f^*g_2 < \rho^{-1}g_1$ ,  $f$  is homotopic to a constant map, where  $\rho \geq 0$  is a constant depending only on  $\sup_{\Sigma_2} K_2$  and on  $\min_{\Sigma_1} K_1$ . This result largely extends the main result of M-T. Wang in *Inventiones Math.* 148 (2002), and the particular case  $\dim(\Sigma_2) = 1$  of the main result in *Comm. Pure. Appl. Math* 57 (2004) (with M-P. Tsui).

Our methods are simpler than Wang's ones, for we use the pseudo-Riemannian structure of  $\Sigma_1 \times \Sigma_2$  instead the Riemannian one used by Wang, and because pseudo-Riemannian geometry has the good signature in the evolution equations, we have better regularity, and therefore we require fewer restrictions on the curvatures and on the map  $f$  itself.