

# Sphere Rigidity in the Euclidean Space

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The well-known Alexandrov theorem [1] says that embedded hypersurfaces in  $\mathbb{R}^{n+1}$  with constant mean curvature are geodesic spheres. This result is not true for only immersed hypersurfaces. For instance, the so-called Wente's tori (see [5]) are examples of compact surfaces with constant mean curvature in  $\mathbb{R}^3$ , which are not geodesic spheres. Other examples of higher genus are known (see [3] for instance).

For immersed hypersurfaces of constant mean curvature, an additional assumption is needed. One condition is given by the Hopf theorem [2], which says that constant mean curvature spheres immersed in  $\mathbb{R}^{n+1}$  are geodesic spheres.

In this talk, we give a new rigidity theorem for spheres, where we replace the topological assumption by a metric assumption. Precisely, it is easy to see that hypersurfaces of  $\mathbb{R}^{n+1}$  with constant mean curvature and constant scalar curvature are geodesic spheres. This result comes from the fact that a hypersurface of constant mean curvature and constant scalar curvature is totally umbilic. Here, we give a new rigidity result with a weaker assumption on the scalar curvature. Namely, we show

**Théorème 1** *Let  $(M^n, g)$  be a compact, connected and oriented Riemannian manifold without boundary isometrically immersed into  $\mathbb{R}^{n+1}$ . Let  $h$  be a positive constant. Then, there exists  $\varepsilon > 0$  such that if*

(1)  $H = h$  and

(2)  $|\text{Scal} - s| \leq \varepsilon,$

*for some constant  $s$ , then  $M$  is the sphere  $\mathbb{S}^n(\frac{1}{h})$  with its standard metric.*

We derive this theorem from results about almost umbilic hypersurfaces that we will prove before, and based on a previous eigenvalue pinching result given in [4]. We will give a word about this eigenvalue pinching result.

## References

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