

The index of a symmetric space

Carlos Olmos

FaMAF-Universidad Nacional de Córdoba, Ciem-CONICET

Conference Symmetry and Shape, in honor of Jürgen Berndt,
Santiago de Compostela, October, 28-31, 2019

The index of a
symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of
Simons holonomy
theorem.

Reflective totally
geodesic
submanifolds.

Sufficient criteria
for reflectivity.

Non-semisimple totally
geodesic submanifolds.

Fixed vectors of the slice
representation.

The index
conjecture.

References

- 1 Introduction.
- 2 Rank and index.
- 3 Applications of Simons holonomy theorem.
- 4 Reflective totally geodesic submanifolds.
- 5 Sufficient criteria for reflectivity.
 - Non-semisimple totally geodesic submanifolds.
 - Fixed vectors of the slice representation.
- 6 The index conjecture.
- 7 References

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Introduction.

This talk is based on joint works with *Jürgen Berndt*.

A submanifold Σ of a Riemannian manifold M is said to be totally geodesic if every geodesic in Σ is also a geodesic in M .

The existence and classification of totally geodesic submanifolds are two fundamental problems in submanifold geometry.

In this lecture we are considering totally geodesic submanifolds of irreducible Riemannian symmetric spaces.

Introduction.

Rank and index.

Applications of
Simons holonomy
theorem.

Reflective totally
geodesic
submanifolds.

Sufficient criteria
for reflectivity.

Non-semisimple totally
geodesic submanifolds.

Fixed vectors of the slice
representation.

The index
conjecture.

References

Introduction.

This talk is based on joint works with *Jürgen Berndt*.

A submanifold Σ of a Riemannian manifold M is said to be totally geodesic if every geodesic in Σ is also a geodesic in M .

The existence and classification of totally geodesic submanifolds are two fundamental problems in submanifold geometry.

In this lecture we are considering totally geodesic submanifolds of irreducible Riemannian symmetric spaces.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Introduction.

This talk is based on joint works with *Jürgen Berndt*.

A submanifold Σ of a Riemannian manifold M is said to be totally geodesic if every geodesic in Σ is also a geodesic in M .

The existence and classification of totally geodesic submanifolds are two fundamental problems in submanifold geometry.

In this lecture we are considering totally geodesic submanifolds of irreducible Riemannian symmetric spaces.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Introduction.

This talk is based on joint works with *Jürgen Berndt*.

A submanifold Σ of a Riemannian manifold M is said to be totally geodesic if every geodesic in Σ is also a geodesic in M .

The existence and classification of totally geodesic submanifolds are two fundamental problems in submanifold geometry.

In this lecture we are considering totally geodesic submanifolds of irreducible Riemannian symmetric spaces.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Introduction.

This talk is based on joint works with *Jürgen Berndt*.

A submanifold Σ of a Riemannian manifold M is said to be totally geodesic if every geodesic in Σ is also a geodesic in M .

The existence and classification of totally geodesic submanifolds are two fundamental problems in submanifold geometry.

In this lecture we are considering totally geodesic submanifolds of irreducible Riemannian symmetric spaces.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

The totally geodesic submanifolds in Riemannian symmetric spaces of rank one were classified by *Joseph Wolf* in 1963.

It is remarkable that the classification of totally geodesic submanifolds in Riemannian symmetric spaces of higher rank is a very complicated and essentially unsolved problem.

Élie Cartan already noticed an algebraic characterization of totally geodesic submanifolds in terms of Lie triple systems.

Although a Lie triple system is an elementary algebraic object, **explicit calculations** with them can be tremendously complicated.

Introduction.

Rank and index.

Applications of
Simons holonomy
theorem.

Reflective totally
geodesic
submanifolds.

Sufficient criteria
for reflectivity.

Non-semisimple totally
geodesic submanifolds.

Fixed vectors of the slice
representation.

The index
conjecture.

References

The totally geodesic submanifolds in Riemannian symmetric spaces of rank one were classified by *Joseph Wolf* in 1963.

It is remarkable that the classification of totally geodesic submanifolds in Riemannian symmetric spaces of higher rank is a very complicated and essentially unsolved problem.

Élie Cartan already noticed an algebraic characterization of totally geodesic submanifolds in terms of Lie triple systems.

Although a Lie triple system is an elementary algebraic object, **explicit calculations** with them can be tremendously complicated.

Introduction.

Rank and index.

Applications of
Simons holonomy
theorem.

Reflective totally
geodesic
submanifolds.

Sufficient criteria
for reflectivity.

Non-semisimple totally
geodesic submanifolds.

Fixed vectors of the slice
representation.

The index
conjecture.

References

The totally geodesic submanifolds in Riemannian symmetric spaces of rank one were classified by *Joseph Wolf* in 1963.

It is remarkable that the classification of totally geodesic submanifolds in Riemannian symmetric spaces of higher rank is a very complicated and essentially unsolved problem.

Élie Cartan already noticed an algebraic characterization of totally geodesic submanifolds in terms of Lie triple systems.

Although a Lie triple system is an elementary algebraic object, **explicit calculations** with them can be tremendously complicated.

Introduction.

Rank and index.

Applications of
Simons holonomy
theorem.

Reflective totally
geodesic
submanifolds.

Sufficient criteria
for reflectivity.

Non-semisimple totally
geodesic submanifolds.

Fixed vectors of the slice
representation.

The index
conjecture.

References

The totally geodesic submanifolds in Riemannian symmetric spaces of rank one were classified by *Joseph Wolf* in 1963.

It is remarkable that the classification of totally geodesic submanifolds in Riemannian symmetric spaces of higher rank is a very complicated and essentially unsolved problem.

Élie Cartan already noticed an algebraic characterization of totally geodesic submanifolds in terms of Lie triple systems.

Although a Lie triple system is an elementary algebraic object, [explicit calculations](#) with them can be tremendously complicated.

Introduction.

Rank and index.

Applications of
Simons holonomy
theorem.

Reflective totally
geodesic
submanifolds.

Sufficient criteria
for reflectivity.

Non-semisimple totally
geodesic submanifolds.

Fixed vectors of the slice
representation.

The index
conjecture.

References

Using the Lie triple system approach, *Sebastian Klein* obtained between 2008-10, in a series of papers, the classification of totally geodesic submanifolds in irreducible Riemannian symmetric spaces of rank two.

No complete classifications are known for totally geodesic submanifolds in irreducible Riemannian symmetric spaces of rank greater than two.

A rather well-known result states that an irreducible Riemannian symmetric space which admits a totally geodesic **hypersurface** must be a space of constant curvature. As far as we know, the first proof of this fact was given by *N. Iwahori* in 1965.

Introduction.

Rank and index.

Applications of
Simons holonomy
theorem.

Reflective totally
geodesic
submanifolds.

Sufficient criteria
for reflectivity.

Non-semisimple totally
geodesic submanifolds.

Fixed vectors of the slice
representation.

The index
conjecture.

References

Using the Lie triple system approach, *Sebastian Klein* obtained between 2008-10, in a series of papers, the classification of totally geodesic submanifolds in irreducible Riemannian symmetric spaces of rank two.

No complete classifications are known for totally geodesic submanifolds in irreducible Riemannian symmetric spaces of rank greater than two.

A rather well-known result states that an irreducible Riemannian symmetric space which admits a totally geodesic **hypersurface** must be a space of constant curvature. As far as we know, the first proof of this fact was given by *N. Iwahori* in 1965.

Introduction.

Rank and index.

Applications of
Simons holonomy
theorem.

Reflective totally
geodesic
submanifolds.

Sufficient criteria
for reflectivity.

Non-semisimple totally
geodesic submanifolds.

Fixed vectors of the slice
representation.

The index
conjecture.

References

Using the Lie triple system approach, *Sebastian Klein* obtained between 2008-10, in a series of papers, the classification of totally geodesic submanifolds in irreducible Riemannian symmetric spaces of rank two.

No complete classifications are known for totally geodesic submanifolds in irreducible Riemannian symmetric spaces of rank greater than two.

A rather well-known result states that an irreducible Riemannian symmetric space which admits a totally geodesic **hypersurface** must be a space of constant curvature. As far as we know, the first proof of this fact was given by *N. Iwahori* in 1965.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Using the Lie triple system approach, *Sebastian Klein* obtained between 2008-10, in a series of papers, the classification of totally geodesic submanifolds in irreducible Riemannian symmetric spaces of rank two.

No complete classifications are known for totally geodesic submanifolds in irreducible Riemannian symmetric spaces of rank greater than two.

A rather well-known result states that an irreducible Riemannian symmetric space which admits a totally geodesic [hypersurface](#) must be a space of constant curvature. As far as we know, the first proof of this fact was given by *N. Iwahori* in 1965.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

In 1980, *A. L. Onishchik* introduced the **index** $i(M)$ of a Riemannian symmetric space M as the **minimal codimension of a totally geodesic submanifold** of M . Onishchik gave an alternative proof for Iwahori's result and also classified the irreducible Riemannian symmetric spaces with index 2.

In this lecture we would like to present a new approach to the index based, essentially, on geometric tools. By means of this approach we were able to determine the index of all symmetric spaces, with the exception of three families of classical type (on which we are still working).

Our point of view also allows us to determine the maximal totally geodesic submanifolds (of symmetric spaces) that are **non-semisimple**.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

In 1980, *A. L. Onishchik* introduced the **index** $i(M)$ of a Riemannian symmetric space M as the **minimal codimension of a totally geodesic submanifold** of M . Onishchik gave an alternative proof for Iwahori's result and also classified the irreducible Riemannian symmetric spaces with index 2.

In this lecture we would like to present a new approach to the index based, essentially, on geometric tools. By means of this approach we were able to determine the index of all symmetric spaces, with the exception of three families of classical type (on which we are still working).

Our point of view also allows us to determine the maximal totally geodesic submanifolds (of symmetric spaces) that are **non-semisimple**.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

In 1980, *A. L. Onishchik* introduced the **index** $i(M)$ of a Riemannian symmetric space M as the **minimal codimension of a totally geodesic submanifold** of M . Onishchik gave an alternative proof for Iwahori's result and also classified the irreducible Riemannian symmetric spaces with index 2.

In this lecture we would like to present a new approach to the index based, essentially, on geometric tools. By means of this approach we were able to determine the index of all symmetric spaces, with the exception of three families of classical type (on which we are still working).

Our point of view also allows us to determine the maximal totally geodesic submanifolds (of symmetric spaces) that are **non-semisimple**.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

In 1980, *A. L. Onishchik* introduced the **index** $i(M)$ of a Riemannian symmetric space M as the **minimal codimension of a totally geodesic submanifold** of M . Onishchik gave an alternative proof for Iwahori's result and also classified the irreducible Riemannian symmetric spaces with index 2.

In this lecture we would like to present a new approach to the index based, essentially, on geometric tools. By means of this approach we were able to determine the index of all symmetric spaces, with the exception of three families of classical type (on which we are still working).

Our point of view also allows us to determine the maximal totally geodesic submanifolds (of symmetric spaces) that are **non-semisimple**.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

In 1980, *A. L. Onishchik* introduced the **index** $i(M)$ of a Riemannian symmetric space M as the **minimal codimension of a totally geodesic submanifold** of M . Onishchik gave an alternative proof for Iwahori's result and also classified the irreducible Riemannian symmetric spaces with index 2.

In this lecture we would like to present a new approach to the index based, essentially, on geometric tools. By means of this approach we were able to determine the index of all symmetric spaces, with the exception of three families of classical type (on which we are still working).

Our point of view also allows us to determine the maximal totally geodesic submanifolds (of symmetric spaces) that are **non-semisimple**.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

In 1980, *A. L. Onishchik* introduced the **index** $i(M)$ of a Riemannian symmetric space M as the **minimal codimension of a totally geodesic submanifold** of M . Onishchik gave an alternative proof for Iwahori's result and also classified the irreducible Riemannian symmetric spaces with index 2.

In this lecture we would like to present a new approach to the index based, essentially, on geometric tools. By means of this approach we were able to determine the index of all symmetric spaces, with the exception of three families of classical type (on which we are still working).

Our point of view also allows us to determine the maximal totally geodesic submanifolds (of symmetric spaces) that are **non-semisimple**.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

In 1980, *A. L. Onishchik* introduced the **index** $i(M)$ of a Riemannian symmetric space M as the **minimal codimension of a totally geodesic submanifold** of M . Onishchik gave an alternative proof for Iwahori's result and also classified the irreducible Riemannian symmetric spaces with index 2.

In this lecture we would like to present a new approach to the index based, essentially, on geometric tools. By means of this approach we were able to determine the index of all symmetric spaces, with the exception of three families of classical type (on which we are still working).

Our point of view also allows us to determine the maximal totally geodesic submanifolds (of symmetric spaces) that are **non-semisimple**.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

In 1980, *A. L. Onishchik* introduced the **index** $i(M)$ of a Riemannian symmetric space M as the **minimal codimension of a totally geodesic submanifold** of M . Onishchik gave an alternative proof for Iwahori's result and also classified the irreducible Riemannian symmetric spaces with index 2.

In this lecture we would like to present a new approach to the index based, essentially, on geometric tools. By means of this approach we were able to determine the index of all symmetric spaces, with the exception of three families of classical type (on which we are still working).

Our point of view also allows us to determine the maximal totally geodesic submanifolds (of symmetric spaces) that are **non-semisimple**.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

In 1980, *A. L. Onishchik* introduced the **index** $i(M)$ of a Riemannian symmetric space M as the **minimal codimension of a totally geodesic submanifold** of M . Onishchik gave an alternative proof for Iwahori's result and also classified the irreducible Riemannian symmetric spaces with index 2.

In this lecture we would like to present a new approach to the index based, essentially, on geometric tools. By means of this approach we were able to determine the index of all symmetric spaces, with the exception of three families of classical type (on which we are still working).

Our point of view also allows us to determine the maximal totally geodesic submanifolds (of symmetric spaces) that are **non-semisimple**.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Rank and index.

The starting point for dealing with the index of a symmetric space is the inequality in the following main result:

Theorem (Berndt-O.)

Let M be an irreducible Riemannian symmetric space. Then

$$rk(M) \leq i(M).$$

Moreover, the equality holds if and only if, up to duality, $M = SL_{k+1}/SO_{k+1}$ or $M = G_k^(\mathbb{R}^{n+k}) = SO_{k+n}^o/SO_k SO_n$*

We prove the inequality $rk(M) \leq i(M)$ by showing the following: *if Σ is a totally geodesic submanifold of a symmetric space M , then there exists a maximal flat F of M that intersects Σ transversally.*

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Rank and index.

The starting point for dealing with the index of a symmetric space is the inequality in the following main result:

Theorem (Berndt-O.)

Let M be an irreducible Riemannian symmetric space. Then

$$rk(M) \leq i(M).$$

Moreover, the equality holds if and only if, up to duality, $M = SL_{k+1}/SO_{k+1}$ or $M = G_k^(\mathbb{R}^{n+k}) = SO_{k+n}^o/SO_k SO_n$*

We prove the inequality $rk(M) \leq i(M)$ by showing the following: *if Σ is a totally geodesic submanifold of a symmetric space M , then there exists a maximal flat F of M that intersects Σ transversally.*

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Rank and index.

The starting point for dealing with the index of a symmetric space is the inequality in the following main result:

Theorem (Berndt-O.)

Let M be an irreducible Riemannian symmetric space. Then

$$rk(M) \leq i(M).$$

Moreover, the equality holds if and only if, up to duality, $M = SL_{k+1}/SO_{k+1}$ or $M = G_k^(\mathbb{R}^{n+k}) = SO_{k+n}^o/SO_k SO_n$*

We prove the inequality $rk(M) \leq i(M)$ by showing the following: *if Σ is a totally geodesic submanifold of a symmetric space M , then there exists a maximal flat F of M that intersects Σ transversally.*

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Rank and index.

The starting point for dealing with the index of a symmetric space is the inequality in the following main result:

Theorem (Berndt-O.)

Let M be an irreducible Riemannian symmetric space. Then

$$rk(M) \leq i(M).$$

Moreover, the equality holds if and only if, up to duality, $M = SL_{k+1}/SO_{k+1}$ or $M = G_k^(\mathbb{R}^{n+k}) = SO_{k+n}^o/SO_k SO_n$*

We prove the inequality $rk(M) \leq i(M)$ by showing the following: *if Σ is a totally geodesic submanifold of a symmetric space M , then there exists a maximal flat F of M that intersects Σ transversally.*

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Rank and index.

The starting point for dealing with the index of a symmetric space is the inequality in the following main result:

Theorem (Berndt-O.)

Let M be an irreducible Riemannian symmetric space. Then

$$rk(M) \leq i(M).$$

Moreover, the equality holds if and only if, up to duality, $M = SL_{k+1}/SO_{k+1}$ or $M = G_k^(\mathbb{R}^{n+k}) = SO_{k+n}^o/SO_k SO_n$*

We prove the inequality $rk(M) \leq i(M)$ by showing the following: if Σ is a totally geodesic submanifold of a symmetric space M , then there exists a maximal flat F of M that intersects Σ transversally.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Rank and index.

The starting point for dealing with the index of a symmetric space is the inequality in the following main result:

Theorem (Berndt-O.)

Let M be an irreducible Riemannian symmetric space. Then

$$rk(M) \leq i(M).$$

Moreover, the equality holds if and only if, up to duality, $M = SL_{k+1}/SO_{k+1}$ or $M = G_k^(\mathbb{R}^{n+k}) = SO_{k+n}^o/SO_k SO_n$*

We prove the inequality $rk(M) \leq i(M)$ by showing the following: *if Σ is a totally geodesic submanifold of a symmetric space M , then there exists a maximal flat F of M that intersects Σ transversally.*

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Rank and index.

The starting point for dealing with the index of a symmetric space is the inequality in the following main result:

Theorem (Berndt-O.)

Let M be an irreducible Riemannian symmetric space. Then

$$rk(M) \leq i(M).$$

Moreover, the equality holds if and only if, up to duality, $M = SL_{k+1}/SO_{k+1}$ or $M = G_k^(\mathbb{R}^{n+k}) = SO_{k+n}^o/SO_k SO_n$*

We prove the inequality $rank(M) \leq i(M)$ by showing the following: *if Σ is a totally geodesic submanifold of a symmetric space M , then there exists a maximal flat F of M that intersects Σ transversally.*

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Rank and index.

The starting point for dealing with the index of a symmetric space is the inequality in the following main result:

Theorem (Berndt-O.)

Let M be an irreducible Riemannian symmetric space. Then

$$rk(M) \leq i(M).$$

Moreover, the equality holds if and only if, up to duality, $M = SL_{k+1}/SO_{k+1}$ or $M = G_k^(\mathbb{R}^{n+k}) = SO_{k+n}^o/SO_k SO_n$*

We prove the inequality $rk(M) \leq i(M)$ by showing the following: *if Σ is a totally geodesic submanifold of a symmetric space M , then there exists a maximal flat F of M that intersects Σ transversally.*

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Rank and index.

The starting point for dealing with the index of a symmetric space is the inequality in the following main result:

Theorem (Berndt-O.)

Let M be an irreducible Riemannian symmetric space. Then

$$rk(M) \leq i(M).$$

Moreover, the equality holds if and only if, up to duality, $M = SL_{k+1}/SO_{k+1}$ or $M = G_k^(\mathbb{R}^{n+k}) = SO_{k+n}^o/SO_k SO_n$*

We prove the inequality $rk(M) \leq i(M)$ by showing the following: *if Σ is a totally geodesic submanifold of a symmetric space M , then there exists a maximal flat F of M that intersects Σ transversally.*

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Rank and index.

The starting point for dealing with the index of a symmetric space is the inequality in the following main result:

Theorem (Berndt-O.)

Let M be an irreducible Riemannian symmetric space. Then

$$rk(M) \leq i(M).$$

Moreover, the equality holds if and only if, up to duality, $M = SL_{k+1}/SO_{k+1}$ or $M = G_k^(\mathbb{R}^{n+k}) = SO_{k+n}^o/SO_k SO_n$*

We prove the inequality $rk(M) \leq i(M)$ by showing the following: *if Σ is a totally geodesic submanifold of a symmetric space M , then there exists a maximal flat F of M that **intersects Σ transversally**.*

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Let us now fix some notation.

$$M = G/K$$

denotes a simply connected symmetric space with Cartan decomposition $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ at $p = [e]$, $\mathfrak{p} \simeq T_p M$,

$$\Sigma \subset M$$

denotes a complete totally geodesic submanifold with $p \in \Sigma$,

$$G^\Sigma$$

is the group of *glide transformations* of Σ , i.e.,

$$\text{Lie}(G^\Sigma) = T_p \Sigma \oplus [T_p \Sigma, T_p \Sigma]$$

$$\tilde{G}^\Sigma := \{g \in G : g\Sigma = \Sigma\} \supset G^\Sigma$$

\tilde{G}^Σ is in general **neither connected nor effective** on M .

Let us now fix some notation.

$$M = G/K$$

denotes a simply connected symmetric space with Cartan decomposition $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ at $p = [e]$, $\mathfrak{p} \simeq T_p M$,

$$\Sigma \subset M$$

denotes a complete totally geodesic submanifold with $p \in \Sigma$,

$$G^\Sigma$$

is the group of *glide transformations* of Σ , i.e.,

$$\text{Lie}(G^\Sigma) = T_p \Sigma \oplus [T_p \Sigma, T_p \Sigma]$$

$$\tilde{G}^\Sigma := \{g \in G : g\Sigma = \Sigma\} \supset G^\Sigma$$

\tilde{G}^Σ is in general **neither connected nor effective** on M .

Let us now fix some notation.

$$M = G/K$$

denotes a simply connected symmetric space with Cartan decomposition $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ at $p = [e]$, $\mathfrak{p} \simeq T_p M$,

$$\Sigma \subset M$$

denotes a complete totally geodesic submanifold with $p \in \Sigma$,

$$G^\Sigma$$

is the group of *glide transformations* of Σ , i.e.,

$$\text{Lie}(G^\Sigma) = T_p \Sigma \oplus [T_p \Sigma, T_p \Sigma]$$

$$\tilde{G}^\Sigma := \{g \in G : g\Sigma = \Sigma\} \supset G^\Sigma$$

\tilde{G}^Σ is in general **neither connected nor effective** on M .

Let us now fix some notation.

$$M = G/K$$

denotes a simply connected symmetric space with Cartan decomposition $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ at $p = [e]$, $\mathfrak{p} \simeq T_p M$,

$$\Sigma \subset M$$

denotes a complete totally geodesic submanifold with $p \in \Sigma$,

$$G^\Sigma$$

is the group of *glide transformations* of Σ , i.e.,

$$\text{Lie}(G^\Sigma) = T_p \Sigma \oplus [T_p \Sigma, T_p \Sigma]$$

$$\tilde{G}^\Sigma := \{g \in G : g\Sigma = \Sigma\} \supset G^\Sigma$$

\tilde{G}^Σ is in general **neither connected nor effective** on M .

Let us now fix some notation.

$$M = G/K$$

denotes a simply connected symmetric space with Cartan decomposition $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ at $p = [e]$, $\mathfrak{p} \simeq T_p M$,

$$\Sigma \subset M$$

denotes a complete totally geodesic submanifold with $p \in \Sigma$,

$$G^\Sigma$$

is the group of *glide transformations* of Σ , i.e.,

$$\text{Lie}(G^\Sigma) = T_p \Sigma \oplus [T_p \Sigma, T_p \Sigma]$$

$$\tilde{G}^\Sigma := \{g \in G : g\Sigma = \Sigma\} \supset G^\Sigma$$

\tilde{G}^Σ is in general **neither connected nor effective** on M .

Let us now fix some notation.

$$M = G/K$$

denotes a simply connected symmetric space with Cartan decomposition $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ at $p = [e]$, $\mathfrak{p} \simeq T_p M$,

$$\Sigma \subset M$$

denotes a complete totally geodesic submanifold with $p \in \Sigma$,

$$G^\Sigma$$

is the group of *glide transformations* of Σ , i.e.,

$$\text{Lie}(G^\Sigma) = T_p \Sigma \oplus [T_p \Sigma, T_p \Sigma]$$

$$\tilde{G}^\Sigma := \{g \in G : g\Sigma = \Sigma\} \supset G^\Sigma$$

\tilde{G}^Σ is in general **neither connected nor effective** on M .

Let us now fix some notation.

$$M = G/K$$

denotes a simply connected symmetric space with Cartan decomposition $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ at $p = [e]$, $\mathfrak{p} \simeq T_p M$,

$$\Sigma \subset M$$

denotes a complete totally geodesic submanifold with $p \in \Sigma$,

$$G^\Sigma$$

is the group of *glide transformations* of Σ , i.e.,

$$\text{Lie}(G^\Sigma) = T_p \Sigma \oplus [T_p \Sigma, T_p \Sigma]$$

$$\tilde{G}^\Sigma := \{g \in G : g\Sigma = \Sigma\} \supset G^\Sigma$$

\tilde{G}^Σ is in general *neither connected nor effective* on M .

Let us now fix some notation.

$$M = G/K$$

denotes a simply connected symmetric space with Cartan decomposition $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ at $p = [e]$, $\mathfrak{p} \simeq T_p M$,

$$\Sigma \subset M$$

denotes a complete totally geodesic submanifold with $p \in \Sigma$,

$$G^\Sigma$$

is the group of *glide transformations* of Σ , i.e.,

$$\text{Lie}(G^\Sigma) = T_p \Sigma \oplus [T_p \Sigma, T_p \Sigma]$$

$$\tilde{G}^\Sigma := \{g \in G : g\Sigma = \Sigma\} \supset G^\Sigma$$

\tilde{G}^Σ is in general *neither connected nor effective* on M .

Let us now fix some notation.

$$M = G/K$$

denotes a simply connected symmetric space with Cartan decomposition $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ at $p = [e]$, $\mathfrak{p} \simeq T_p M$,

$$\Sigma \subset M$$

denotes a complete totally geodesic submanifold with $p \in \Sigma$,

$$G^\Sigma$$

is the group of *glide transformations* of Σ , i.e.,

$$\text{Lie}(G^\Sigma) = T_p \Sigma \oplus [T_p \Sigma, T_p \Sigma]$$

$$\tilde{G}^\Sigma := \{g \in G : g\Sigma = \Sigma\} \supset G^\Sigma$$

\tilde{G}^Σ is in general **neither connected nor effective** on M .

Let us now fix some notation.

$$M = G/K$$

denotes a simply connected symmetric space with Cartan decomposition $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ at $p = [e]$, $\mathfrak{p} \simeq T_p M$,

$$\Sigma \subset M$$

denotes a complete totally geodesic submanifold with $p \in \Sigma$,

$$G^\Sigma$$

is the group of *glide transformations* of Σ , i.e.,

$$\text{Lie}(G^\Sigma) = T_p \Sigma \oplus [T_p \Sigma, T_p \Sigma]$$

$$\tilde{G}^\Sigma := \{g \in G : g\Sigma = \Sigma\} \supset G^\Sigma$$

\tilde{G}^Σ is in general **neither connected nor effective** on M .

The *full slice representation* $\tilde{\rho} : \tilde{G}_\rho^\Sigma \rightarrow O(\nu_\rho \Sigma)$, from the full isotropy subgroup into the orthogonal group the normal space, is defined by

$$\tilde{\rho}(g) = (dg)|_{\nu_\rho \Sigma}$$

The slice representation $\rho : G_\rho^\Sigma \rightarrow O(\nu_\rho \Sigma)$ is

$$\rho = \tilde{\rho}|_{G_\rho^\Sigma}$$

If M is of the non-compact type then G_ρ^Σ is connected, since Σ is simply connected and so $\rho : G_\rho^\Sigma \rightarrow SO(\nu_\rho \Sigma)$.

For our purposes, from duality, we may assume that M is of the non-compact type.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

The *full slice representation* $\tilde{\rho} : \tilde{G}_\rho^\Sigma \rightarrow O(\nu_\rho \Sigma)$, from the full isotropy subgroup into the orthogonal group the normal space, is defined by

$$\tilde{\rho}(g) = (dg)|_{\nu_\rho \Sigma}$$

The slice representation $\rho : G_\rho^\Sigma \rightarrow O(\nu_\rho \Sigma)$ is

$$\rho = \tilde{\rho}|_{G_\rho^\Sigma}$$

If M is of the non-compact type then G_ρ^Σ is connected, since Σ is simply connected and so $\rho : G_\rho^\Sigma \rightarrow SO(\nu_\rho \Sigma)$.

For our purposes, from duality, we may assume that M is of the non-compact type.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

The *full slice representation* $\tilde{\rho} : \tilde{G}_\rho^\Sigma \rightarrow O(\nu_\rho \Sigma)$, from the full isotropy subgroup into the orthogonal group the normal space, is defined by

$$\tilde{\rho}(g) = (dg)|_{\nu_\rho \Sigma}$$

The *slice representation* $\rho : G_\rho^\Sigma \rightarrow O(\nu_\rho \Sigma)$ is

$$\rho = \tilde{\rho}|_{G_\rho^\Sigma}$$

If M is of the non-compact type then G_ρ^Σ is connected, since Σ is simply connected and so $\rho : G_\rho^\Sigma \rightarrow SO(\nu_\rho \Sigma)$.

For our purposes, from duality, we may assume that M is of the non-compact type.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

The *full slice representation* $\tilde{\rho} : \tilde{G}_\rho^\Sigma \rightarrow O(\nu_\rho \Sigma)$, from the full isotropy subgroup into the orthogonal group the normal space, is defined by

$$\tilde{\rho}(g) = (dg)|_{\nu_\rho \Sigma}$$

The slice representation $\rho : G_\rho^\Sigma \rightarrow O(\nu_\rho \Sigma)$ is

$$\rho = \tilde{\rho}|_{G_\rho^\Sigma}$$

If M is of the non-compact type then G_ρ^Σ is connected, since Σ is simply connected and so $\rho : G_\rho^\Sigma \rightarrow SO(\nu_\rho \Sigma)$.

For our purposes, from duality, we may assume that M is of the non-compact type.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

The *full slice representation* $\tilde{\rho} : \tilde{G}_\rho^\Sigma \rightarrow O(\nu_\rho \Sigma)$, from the full isotropy subgroup into the orthogonal group the normal space, is defined by

$$\tilde{\rho}(g) = (dg)|_{\nu_\rho \Sigma}$$

The *slice representation* $\rho : G_\rho^\Sigma \rightarrow O(\nu_\rho \Sigma)$ is

$$\rho = \tilde{\rho}|_{G_\rho^\Sigma}$$

If M is of the non-compact type then G_ρ^Σ is connected, since Σ is simply connected and so $\rho : G_\rho^\Sigma \rightarrow SO(\nu_\rho \Sigma)$.

For our purposes, from duality, we may assume that M is of the non-compact type.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

The *full slice representation* $\tilde{\rho} : \tilde{G}_\rho^\Sigma \rightarrow O(\nu_\rho \Sigma)$, from the full isotropy subgroup into the orthogonal group the normal space, is defined by

$$\tilde{\rho}(g) = (dg)|_{\nu_\rho \Sigma}$$

The *slice representation* $\rho : G_\rho^\Sigma \rightarrow O(\nu_\rho \Sigma)$ is

$$\rho = \tilde{\rho}|_{G_\rho^\Sigma}$$

If M is of the non-compact type then G_ρ^Σ is connected, since Σ is simply connected and so $\rho : G_\rho^\Sigma \rightarrow SO(\nu_\rho \Sigma)$.

For our purposes, from duality, we may assume that M is of the non-compact type.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

The *full slice representation* $\tilde{\rho} : \tilde{G}_\rho^\Sigma \rightarrow O(\nu_\rho \Sigma)$, from the full isotropy subgroup into the orthogonal group the normal space, is defined by

$$\tilde{\rho}(g) = (dg)|_{\nu_\rho \Sigma}$$

The *slice representation* $\rho : G_\rho^\Sigma \rightarrow O(\nu_\rho \Sigma)$ is

$$\rho = \tilde{\rho}|_{G_\rho^\Sigma}$$

If M is of the non-compact type then G_ρ^Σ is connected, since Σ is simply connected and so $\rho : G_\rho^\Sigma \rightarrow SO(\nu_\rho \Sigma)$.

For our purposes, from duality, we may assume that M is of the non-compact type.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

The *full slice representation* $\tilde{\rho} : \tilde{G}_\rho^\Sigma \rightarrow O(\nu_\rho \Sigma)$, from the full isotropy subgroup into the orthogonal group the normal space, is defined by

$$\tilde{\rho}(g) = (dg)|_{\nu_\rho \Sigma}$$

The *slice representation* $\rho : G_\rho^\Sigma \rightarrow O(\nu_\rho \Sigma)$ is

$$\rho = \tilde{\rho}|_{G_\rho^\Sigma}$$

If M is of the non-compact type then G_ρ^Σ is connected, since Σ is simply connected and so $\rho : G_\rho^\Sigma \rightarrow SO(\nu_\rho \Sigma)$.

For our purposes, from duality, we may assume that M is of the non-compact type.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

The *full slice representation* $\tilde{\rho} : \tilde{G}_\rho^\Sigma \rightarrow O(\nu_\rho \Sigma)$, from the full isotropy subgroup into the orthogonal group the normal space, is defined by

$$\tilde{\rho}(g) = (dg)|_{\nu_\rho \Sigma}$$

The *slice representation* $\rho : G_\rho^\Sigma \rightarrow O(\nu_\rho \Sigma)$ is

$$\rho = \tilde{\rho}|_{G_\rho^\Sigma}$$

If M is of the non-compact type then G_ρ^Σ is connected, since Σ is simply connected and so $\rho : G_\rho^\Sigma \rightarrow SO(\nu_\rho \Sigma)$.

For our purposes, from duality, we may assume that M is of the non-compact type.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

An application of Simons holonomy theorem.

We now present a second auxiliary result which follows easily, in rank at least 2, from Simons theorem on holonomy systems.

Slice Lemma (Berndt-O.; Berndt-O.-Rodríguez)

Let Σ be a non-flat totally geodesic submanifold of an irreducible symmetric space M which is not of constant curvature. Then the slice representation $\rho : (G_\rho^\Sigma)^\circ \rightarrow SO(\nu_\rho \Sigma)$ is non-trivial.

The above theorem generalizes Iwahori's result.

It is interesting to remark that the image of the slice representation is the **normal holonomy** of Σ . So, this representation is trivial if and only if the normal bundle of Σ is flat.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

An application of Simons holonomy theorem.

We now present a second auxiliary result which follows easily, in rank at least 2, from Simons theorem on holonomy systems.

Slice Lemma (Berndt-O.; Berndt-O.-Rodríguez)

Let Σ be a non-flat totally geodesic submanifold of an irreducible symmetric space M which is not of constant curvature. Then the slice representation $\rho : (G_{\rho}^{\Sigma})^{\circ} \rightarrow SO(\nu_{\rho}\Sigma)$ is non-trivial.

The above theorem generalizes Iwahori's result.

It is interesting to remark that the image of the slice representation is the **normal holonomy** of Σ . So, this representation is trivial if and only if the normal bundle of Σ is flat.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

An application of Simons holonomy theorem.

We now present a second auxiliary result which follows easily, in rank at least 2, from Simons theorem on holonomy systems.

Slice Lemma (Berndt-O.; Berndt-O.-Rodríguez)

Let Σ be a non-flat totally geodesic submanifold of an irreducible symmetric space M which is not of constant curvature. Then the slice representation $\rho : (G_p^\Sigma)^\circ \rightarrow SO(\nu_p \Sigma)$ is non-trivial.

The above theorem generalizes Iwahori's result.

It is interesting to remark that the image of the slice representation is the **normal holonomy** of Σ . So, this representation is trivial if and only if the normal bundle of Σ is flat.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

An application of Simons holonomy theorem.

We now present a second auxiliary result which follows easily, in rank at least 2, from Simons theorem on holonomy systems.

Slice Lemma (Berndt-O.; Berndt-O.-Rodríguez)

Let Σ be a non-flat totally geodesic submanifold of an irreducible symmetric space M which is not of constant curvature. Then the slice representation $\rho : (G_p^\Sigma)^\circ \rightarrow SO(\nu_p \Sigma)$ is non-trivial.

The above theorem generalizes Iwahori's result.

It is interesting to remark that the image of the slice representation is the **normal holonomy** of Σ . So, this representation is trivial if and only if the normal bundle of Σ is flat.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

An application of Simons holonomy theorem.

We now present a second auxiliary result which follows easily, in rank at least 2, from Simons theorem on holonomy systems.

Slice Lemma (Berndt-O.; Berndt-O.-Rodríguez)

Let Σ be a non-flat totally geodesic submanifold of an irreducible symmetric space M which is not of constant curvature. Then the slice representation $\rho : (G_\rho^\Sigma)^\circ \rightarrow SO(\nu_\rho \Sigma)$ is non-trivial.

The above theorem generalizes Iwahori's result.

It is interesting to remark that the image of the slice representation is the **normal holonomy** of Σ . So, this representation is trivial if and only if the normal bundle of Σ is flat.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

An application of Simons holonomy theorem.

We now present a second auxiliary result which follows easily, in rank at least 2, from Simons theorem on holonomy systems.

Slice Lemma (Berndt-O.; Berndt-O.-Rodríguez)

Let Σ be a non-flat totally geodesic submanifold of an irreducible symmetric space M which is not of constant curvature. Then the slice representation $\rho : (G_\rho^\Sigma)^\circ \rightarrow SO(\nu_\rho \Sigma)$ is non-trivial.

The above theorem generalizes Iwahori's result.

It is interesting to remark that the image of the slice representation is the **normal holonomy** of Σ . So, this representation is trivial if and only if the normal bundle of Σ is flat.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

An application of Simons holonomy theorem.

We now present a second auxiliary result which follows easily, in rank at least 2, from Simons theorem on holonomy systems.

Slice Lemma (Berndt-O.; Berndt-O.-Rodríguez)

Let Σ be a non-flat totally geodesic submanifold of an irreducible symmetric space M which is not of constant curvature. Then the slice representation $\rho : (G_p^\Sigma)^\circ \rightarrow SO(\nu_p \Sigma)$ is non-trivial.

The above theorem generalizes Iwahori's result.

It is interesting to remark that the image of the slice representation is the **normal holonomy** of Σ . So, this representation is trivial if and only if the normal bundle of Σ is flat.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

An application of Simons holonomy theorem.

We now present a second auxiliary result which follows easily, in rank at least 2, from Simons theorem on holonomy systems.

Slice Lemma (Berndt-O.; Berndt-O.-Rodríguez)

Let Σ be a non-flat totally geodesic submanifold of an irreducible symmetric space M which is not of constant curvature. Then the slice representation $\rho : (G_{\rho}^{\Sigma})^{\circ} \rightarrow SO(\nu_{\rho}\Sigma)$ is non-trivial.

The above theorem generalizes Iwahori's result.

It is interesting to remark that the image of the slice representation is the **normal holonomy** of Σ . So, this representation is trivial if and only if the normal bundle of Σ is flat.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

An application of Simons holonomy theorem.

We now present a second auxiliary result which follows easily, in rank at least 2, from Simons theorem on holonomy systems.

Slice Lemma (Berndt-O.; Berndt-O.-Rodríguez)

Let Σ be a non-flat totally geodesic submanifold of an irreducible symmetric space M which is not of constant curvature. Then the slice representation $\rho : (G_p^\Sigma)^\circ \rightarrow SO(\nu_p \Sigma)$ is non-trivial.

The above theorem generalizes Iwahori's result.

It is interesting to remark that the image of the slice representation is the **normal holonomy** of Σ . So, this representation is trivial if and only if the normal bundle of Σ is flat.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Reflective totally geodesic submanifolds.

A totally geodesic submanifold Σ of a symmetric space M is called *reflective* if the exponential of the normal space $\exp_p(\nu_p\Sigma)$ is also a totally geodesic submanifold of M .

Equivalently, Σ is reflective if $T_p\Sigma$ and $\nu_p\Sigma$ are both Lie triple systems.

One has that Σ is reflective if and only if the reflection of M in Σ is an isometry.

Reflective submanifolds of symmetric spaces were classified by *D. S. P. Leung* in the 70's.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Reflective totally geodesic submanifolds.

A totally geodesic submanifold Σ of a symmetric space M is called *reflective* if the exponential of the normal space $\exp_p(\nu_p\Sigma)$ is also a totally geodesic submanifold of M .

Equivalently, Σ is reflective if $T_p\Sigma$ and $\nu_p\Sigma$ are both Lie triple systems.

One has that Σ is reflective if and only if the reflection of M in Σ is an isometry.

Reflective submanifolds of symmetric spaces were classified by *D. S. P. Leung* in the 70's.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Reflective totally geodesic submanifolds.

A totally geodesic submanifold Σ of a symmetric space M is called *reflective* if the exponential of the normal space $\exp_p(\nu_p\Sigma)$ is also a totally geodesic submanifold of M .

Equivalently, Σ is reflective if $T_p\Sigma$ and $\nu_p\Sigma$ are both Lie triple systems.

One has that Σ is reflective if and only if the reflection of M in Σ is an isometry.

Reflective submanifolds of symmetric spaces were classified by *D. S. P. Leung* in the 70's.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Reflective totally geodesic submanifolds.

A totally geodesic submanifold Σ of a symmetric space M is called *reflective* if the exponential of the normal space $\exp_p(\nu_p\Sigma)$ is also a totally geodesic submanifold of M .

Equivalently, Σ is reflective if $T_p\Sigma$ and $\nu_p\Sigma$ are both Lie triple systems.

One has that Σ is reflective if and only if the reflection of M in Σ is an isometry.

Reflective submanifolds of symmetric spaces were classified by *D. S. P. Leung* in the 70's.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Reflective totally geodesic submanifolds.

A totally geodesic submanifold Σ of a symmetric space M is called *reflective* if the exponential of the normal space $\exp_p(\nu_p\Sigma)$ is also a totally geodesic submanifold of M .

Equivalently, Σ is reflective if $T_p\Sigma$ and $\nu_p\Sigma$ are both Lie triple systems.

One has that Σ is reflective if and only if the reflection of M in Σ is an isometry.

Reflective submanifolds of symmetric spaces were classified by *D. S. P. Leung* in the 70's.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Sufficient criteria for reflectivity.

By making use of the Slice Lemma, we proved the following results:

Proposition (Berndt-O.; Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible Riemannian symmetric space with $\text{rk}(M) \geq 2$, where (G, K) is an effective Riemannian symmetric pair. Let Σ be a semisimple totally geodesic submanifold of M with $p = [e] \in \Sigma$. Then Σ is reflective if and only if the kernel of the full slice representation $\tilde{\rho} : \tilde{G}_p^\Sigma \rightarrow O(\nu_p \Sigma)$ is non-trivial.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Sufficient criteria for reflectivity.

By making use of the Slice Lemma, we proved the following results:

Proposition (Berndt-O.; Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible Riemannian symmetric space with $\text{rk}(M) \geq 2$, where (G, K) is an effective Riemannian symmetric pair. Let Σ be a semisimple totally geodesic submanifold of M with $p = [e] \in \Sigma$. Then Σ is reflective if and only if the kernel of the full slice representation $\tilde{\rho} : \tilde{G}_p^\Sigma \rightarrow O(\nu_p \Sigma)$ is non-trivial.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Sufficient criteria for reflectivity.

By making use of the Slice Lemma, we proved the following results:

Proposition (Berndt-O.; Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible Riemannian symmetric space with $\text{rk}(M) \geq 2$, where (G, K) is an effective Riemannian symmetric pair. Let Σ be a semisimple totally geodesic submanifold of M with $p = [e] \in \Sigma$. Then Σ is reflective if and only if the kernel of the full slice representation $\tilde{\rho} : \tilde{G}_p^\Sigma \rightarrow O(\nu_p \Sigma)$ is non-trivial.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Sufficient criteria for reflectivity.

By making use of the Slice Lemma, we proved the following results:

Proposition (Berndt-O.; Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible Riemannian symmetric space with $\text{rk}(M) \geq 2$, where (G, K) is an effective Riemannian symmetric pair. Let Σ be a semisimple totally geodesic submanifold of M with $p = [e] \in \Sigma$. Then Σ is reflective if and only if the kernel of the full slice representation $\tilde{\rho} : \tilde{G}_p^\Sigma \rightarrow O(\nu_p \Sigma)$ is non-trivial.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Sufficient criteria for reflectivity.

By making use of the Slice Lemma, we proved the following results:

Proposition (Berndt-O.; Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible Riemannian symmetric space with $\text{rk}(M) \geq 2$, where (G, K) is an effective Riemannian symmetric pair. Let Σ be a semisimple totally geodesic submanifold of M with $p = [e] \in \Sigma$. Then Σ is reflective if and only if the kernel of the full slice representation $\tilde{\rho} : \tilde{G}_p^\Sigma \rightarrow O(\nu_p \Sigma)$ is non-trivial.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Sufficient criteria for reflectivity.

By making use of the Slice Lemma, we proved the following results:

Proposition (Berndt-O.; Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible Riemannian symmetric space with $\text{rk}(M) \geq 2$, where (G, K) is an effective Riemannian symmetric pair. Let Σ be a semisimple totally geodesic submanifold of M with $p = [e] \in \Sigma$. Then Σ is reflective if and only if the kernel of the full slice representation $\tilde{\rho} : \tilde{G}_p^\Sigma \rightarrow O(\nu_p \Sigma)$ is non-trivial.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Corollary (Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible simply connected Riemannian symmetric space with $\text{rk}(M) \geq 2$. Let Σ_1, Σ_2 be connected, complete, totally geodesic submanifolds of M with $\Sigma_1 \subseteq \Sigma_2$. If Σ_1 is reflective, then Σ_2 is reflective.

We also have the following useful criterion:

Theorem (Berndt-O.-Rodríguez)

Let Σ be a maximal semisimple totally geodesic submanifold of an irreducible symmetric space $M = G/K$. If $\dim(\tilde{G}^\Sigma) > \dim(G^\Sigma)$, then Σ is reflective.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Corollary (Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible simply connected Riemannian symmetric space with $\text{rk}(M) \geq 2$. Let Σ_1, Σ_2 be connected, complete, totally geodesic submanifolds of M with $\Sigma_1 \subseteq \Sigma_2$. If Σ_1 is reflective, then Σ_2 is reflective.

We also have the following useful criterion:

Theorem (Berndt-O.-Rodríguez)

Let Σ be a maximal semisimple totally geodesic submanifold of an irreducible symmetric space $M = G/K$. If $\dim(\tilde{G}^\Sigma) > \dim(G^\Sigma)$, then Σ is reflective.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Corollary (Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible simply connected Riemannian symmetric space with $\text{rk}(M) \geq 2$. Let Σ_1, Σ_2 be connected, complete, totally geodesic submanifolds of M with $\Sigma_1 \subseteq \Sigma_2$. If Σ_1 is reflective, then Σ_2 is reflective.

We also have the following useful criterion:

Theorem (Berndt-O.-Rodríguez)

Let Σ be a maximal semisimple totally geodesic submanifold of an irreducible symmetric space $M = G/K$. If $\dim(\tilde{G}^\Sigma) > \dim(G^\Sigma)$, then Σ is reflective.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Corollary (Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible simply connected Riemannian symmetric space with $\text{rk}(M) \geq 2$. Let Σ_1, Σ_2 be connected, complete, totally geodesic submanifolds of M with $\Sigma_1 \subseteq \Sigma_2$. If Σ_1 is reflective, then Σ_2 is reflective.

We also have the following useful criterion:

Theorem (Berndt-O.-Rodríguez)

Let Σ be a maximal semisimple totally geodesic submanifold of an irreducible symmetric space $M = G/K$. If $\dim(\tilde{G}^\Sigma) > \dim(G^\Sigma)$, then Σ is reflective.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Corollary (Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible simply connected Riemannian symmetric space with $\text{rk}(M) \geq 2$. Let Σ_1, Σ_2 be connected, complete, totally geodesic submanifolds of M with $\Sigma_1 \subseteq \Sigma_2$. If Σ_1 is reflective, then Σ_2 is reflective.

We also have the following useful criterion:

Theorem (Berndt-O.-Rodríguez)

Let Σ be a maximal semisimple totally geodesic submanifold of an irreducible symmetric space $M = G/K$. If $\dim(\tilde{G}^\Sigma) > \dim(G^\Sigma)$, then Σ is reflective.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Corollary (Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible simply connected Riemannian symmetric space with $\text{rk}(M) \geq 2$. Let Σ_1, Σ_2 be connected, complete, totally geodesic submanifolds of M with $\Sigma_1 \subseteq \Sigma_2$. If Σ_1 is reflective, then Σ_2 is reflective.

We also have the following useful criterion:

Theorem (Berndt-O.-Rodríguez)

Let Σ be a maximal semisimple totally geodesic submanifold of an irreducible symmetric space $M = G/K$. If $\dim(\tilde{G}^\Sigma) > \dim(G^\Sigma)$, then Σ is reflective.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Remark. Let us consider the (almost effective) symmetric pair $(G^\Sigma, G_\rho^\Sigma)$. The principal orbits, of the G_ρ^Σ -action on $T_\rho\Sigma$, have dimension $\dim(\Sigma) - \text{rk}(\Sigma)$. Then

$$\dim(\Sigma) - \text{rk}(M) \leq \dim(G_\rho^\Sigma)$$

On the other hand, the dimension of the image of the slice representation $\rho(G_\rho^\Sigma) \subset \tilde{\rho}(\tilde{G}_\rho^\Sigma)$ is bounded from above by $\dim(\mathcal{O}(\nu_\rho(\Sigma))) = \frac{1}{2}k(k-1)$, where k is the codimension of Σ .

Therefore, if $\frac{1}{2}k(k-1) < \dim(\Sigma) - \text{rk}(M)$, the full slice representation **cannot be injective**. Then

Corollary (Berndt-O.)

Let Σ^n be a totally geodesic submanifold of a symmetric space M^{n+k} . If $\frac{1}{2}k(k-1) < n - \text{rk}(M)$, then Σ is reflective.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Remark. Let us consider the (almost effective) symmetric pair $(G^\Sigma, G_\rho^\Sigma)$. The principal orbits, of the G_ρ^Σ -action on $T_\rho\Sigma$, have dimension $\dim(\Sigma) - \text{rk}(\Sigma)$. Then

$$\dim(\Sigma) - \text{rk}(M) \leq \dim(G_\rho^\Sigma)$$

On the other hand, the dimension of the image of the slice representation $\rho(G_\rho^\Sigma) \subset \tilde{\rho}(\tilde{G}_\rho^\Sigma)$ is bounded from above by $\dim(\mathcal{O}(\nu_\rho(\Sigma))) = \frac{1}{2}k(k-1)$, where k is the codimension of Σ .

Therefore, if $\frac{1}{2}k(k-1) < \dim(\Sigma) - \text{rk}(M)$, the full slice representation **cannot be injective**. Then

Corollary (Berndt-O.)

Let Σ^n be a totally geodesic submanifold of a symmetric space M^{n+k} . If $\frac{1}{2}k(k-1) < n - \text{rk}(M)$, then Σ is reflective.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Remark. Let us consider the (almost effective) symmetric pair $(G^\Sigma, G_\rho^\Sigma)$. The principal orbits, of the G_ρ^Σ -action on $T_\rho\Sigma$, have dimension $\dim(\Sigma) - \text{rk}(\Sigma)$. Then

$$\dim(\Sigma) - \text{rk}(M) \leq \dim(G_\rho^\Sigma)$$

On the other hand, the dimension of the image of the slice representation $\rho(G_\rho^\Sigma) \subset \tilde{\rho}(\tilde{G}_\rho^\Sigma)$ is bounded from above by $\dim(\mathcal{O}(\nu_\rho(\Sigma))) = \frac{1}{2}k(k-1)$, where k is the codimension of Σ .

Therefore, if $\frac{1}{2}k(k-1) < \dim(\Sigma) - \text{rk}(M)$, the full slice representation **cannot be injective**. Then

Corollary (Berndt-O.)

Let Σ^n be a totally geodesic submanifold of a symmetric space M^{n+k} . If $\frac{1}{2}k(k-1) < n - \text{rk}(M)$, then Σ is reflective.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Remark. Let us consider the (almost effective) symmetric pair (G^Σ, G_p^Σ) . The principal orbits, of the G_p^Σ -action on $T_p\Sigma$, have dimension $\dim(\Sigma) - \text{rk}(\Sigma)$. Then

$$\dim(\Sigma) - \text{rk}(M) \leq \dim(G_p^\Sigma)$$

On the other hand, the dimension of the image of the slice representation $\rho(G_p^\Sigma) \subset \tilde{\rho}(\tilde{G}_p^\Sigma)$ is bounded from above by $\dim(\mathcal{O}(\nu_p(\Sigma))) = \frac{1}{2}k(k-1)$, where k is the codimension of Σ .

Therefore, if $\frac{1}{2}k(k-1) < \dim(\Sigma) - \text{rk}(M)$, the full slice representation **cannot be injective**. Then

Corollary (Berndt-O.)

Let Σ^n be a totally geodesic submanifold of a symmetric space M^{n+k} . If $\frac{1}{2}k(k-1) < n - \text{rk}(M)$, then Σ is reflective.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Remark. Let us consider the (almost effective) symmetric pair (G^Σ, G_p^Σ) . The principal orbits, of the G_p^Σ -action on $T_p\Sigma$, have dimension $\dim(\Sigma) - \text{rk}(\Sigma)$. Then

$$\dim(\Sigma) - \text{rk}(M) \leq \dim(G_p^\Sigma)$$

On the other hand, the dimension of the image of the slice representation $\rho(G_p^\Sigma) \subset \tilde{\rho}(\tilde{G}_p^\Sigma)$ is bounded from above by $\dim(\mathcal{O}(\nu_p(\Sigma))) = \frac{1}{2}k(k-1)$, where k is the codimension of Σ .

Therefore, if $\frac{1}{2}k(k-1) < \dim(\Sigma) - \text{rk}(M)$, the full slice representation **cannot be injective**. Then

Corollary (Berndt-O.)

Let Σ^n be a totally geodesic submanifold of a symmetric space M^{n+k} . If $\frac{1}{2}k(k-1) < n - \text{rk}(M)$, then Σ is reflective.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Remark. Let us consider the (almost effective) symmetric pair (G^Σ, G_p^Σ) . The principal orbits, of the G_p^Σ -action on $T_p\Sigma$, have dimension $\dim(\Sigma) - \text{rk}(\Sigma)$. Then

$$\dim(\Sigma) - \text{rk}(M) \leq \dim(G_p^\Sigma)$$

On the other hand, the dimension of the image of the slice representation $\rho(G_p^\Sigma) \subset \tilde{\rho}(\tilde{G}_p^\Sigma)$ is bounded from above by $\dim(\mathcal{O}(\nu_p(\Sigma))) = \frac{1}{2}k(k-1)$, where k is the codimension of Σ .

Therefore, if $\frac{1}{2}k(k-1) < \dim(\Sigma) - \text{rk}(M)$, the full slice representation **cannot be injective**. Then

Corollary (Berndt-O.)

Let Σ^n be a totally geodesic submanifold of a symmetric space M^{n+k} . If $\frac{1}{2}k(k-1) < n - \text{rk}(M)$, then Σ is reflective.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Remark. Let us consider the (almost effective) symmetric pair (G^Σ, G_p^Σ) . The principal orbits, of the G_p^Σ -action on $T_p\Sigma$, have dimension $\dim(\Sigma) - \text{rk}(\Sigma)$. Then

$$\dim(\Sigma) - \text{rk}(M) \leq \dim(G_p^\Sigma)$$

On the other hand, the dimension of the image of the slice representation $\rho(G_p^\Sigma) \subset \tilde{\rho}(\tilde{G}_p^\Sigma)$ is bounded from above by $\dim(\mathcal{O}(\nu_p(\Sigma))) = \frac{1}{2}k(k-1)$, where k is the codimension of Σ .

Therefore, if $\frac{1}{2}k(k-1) < \dim(\Sigma) - \text{rk}(M)$, the full slice representation **cannot be injective**. Then

Corollary (Berndt-O.)

Let Σ^n be a totally geodesic submanifold of a symmetric space M^{n+k} . If $\frac{1}{2}k(k-1) < n - \text{rk}(M)$, then Σ is reflective.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Remark. Let us consider the (almost effective) symmetric pair (G^Σ, G_p^Σ) . The principal orbits, of the G_p^Σ -action on $T_p\Sigma$, have dimension $\dim(\Sigma) - \text{rk}(\Sigma)$. Then

$$\dim(\Sigma) - \text{rk}(M) \leq \dim(G_p^\Sigma)$$

On the other hand, the dimension of the image of the slice representation $\rho(G_p^\Sigma) \subset \tilde{\rho}(\tilde{G}_p^\Sigma)$ is bounded from above by $\dim(\mathcal{O}(\nu_p(\Sigma))) = \frac{1}{2}k(k-1)$, where k is the codimension of Σ .

Therefore, if $\frac{1}{2}k(k-1) < \dim(\Sigma) - \text{rk}(M)$, the full slice representation **cannot be injective**. Then

Corollary (Berndt-O.)

Let Σ^n be a totally geodesic submanifold of a symmetric space M^{n+k} . If $\frac{1}{2}k(k-1) < n - \text{rk}(M)$, then Σ is reflective.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Remark. Let us consider the (almost effective) symmetric pair (G^Σ, G_p^Σ) . The principal orbits, of the G_p^Σ -action on $T_p\Sigma$, have dimension $\dim(\Sigma) - \text{rk}(\Sigma)$. Then

$$\dim(\Sigma) - \text{rk}(M) \leq \dim(G_p^\Sigma)$$

On the other hand, the dimension of the image of the slice representation $\rho(G_p^\Sigma) \subset \tilde{\rho}(\tilde{G}_p^\Sigma)$ is bounded from above by $\dim(\mathcal{O}(\nu_p(\Sigma))) = \frac{1}{2}k(k-1)$, where k is the codimension of Σ .

Therefore, if $\frac{1}{2}k(k-1) < \dim(\Sigma) - \text{rk}(M)$, the full slice representation **cannot be injective**. Then

Corollary (Berndt-O.)

Let Σ^n be a totally geodesic submanifold of a symmetric space M^{n+k} . If $\frac{1}{2}k(k-1) < n - \text{rk}(M)$, then Σ is reflective.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Remark. Let us consider the (almost effective) symmetric pair (G^Σ, G_p^Σ) . The principal orbits, of the G_p^Σ -action on $T_p\Sigma$, have dimension $\dim(\Sigma) - \text{rk}(\Sigma)$. Then

$$\dim(\Sigma) - \text{rk}(M) \leq \dim(G_p^\Sigma)$$

On the other hand, the dimension of the image of the slice representation $\rho(G_p^\Sigma) \subset \tilde{\rho}(\tilde{G}_p^\Sigma)$ is bounded from above by $\dim(\mathcal{O}(\nu_p(\Sigma))) = \frac{1}{2}k(k-1)$, where k is the codimension of Σ .

Therefore, if $\frac{1}{2}k(k-1) < \dim(\Sigma) - \text{rk}(M)$, the full slice representation **cannot be injective**. Then

Corollary (Berndt-O.)

Let Σ^n be a totally geodesic submanifold of a symmetric space M^{n+k} . If $\frac{1}{2}k(k-1) < n - \text{rk}(M)$, then Σ is reflective.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Non-semisimple totally geodesic submanifolds.

The index of a symmetric space

Carlos Olmos

If $\Sigma \subset M = G/K$ is totally geodesic and $p \in \Sigma$, then $T_p\Sigma$ is a Lie triple system of \mathfrak{p} . Assume that Σ is **not semisimple**. Then there exists $0 \neq v \in T_p\Sigma$ such that $[v, T_p\Sigma] = 0$. Therefore $T_p\Sigma$ must be contained in the Lie triple system

$$\mathcal{C}(v) = \{z \in \mathfrak{p} : [v, z] = 0\},$$

the centralizer of v in \mathfrak{p} . One has that $\mathcal{C}(v)$ coincides with the normal space $\nu_v(K.v)$ of the isotropy orbit. If Σ is **maximal**, then the orbit $K.v$ must be most singular and hence

$$T_p\Sigma \cap \nu_v^\perp$$

is semisimple.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Non-semisimple totally geodesic submanifolds.

The index of a symmetric space

Carlos Olmos

If $\Sigma \subset M = G/K$ is totally geodesic and $p \in \Sigma$, then $T_p\Sigma$ is a Lie triple system of \mathfrak{p} . Assume that Σ is **not semisimple**. Then there exists $0 \neq v \in T_p\Sigma$ such that $[v, T_p\Sigma] = 0$. Therefore $T_p\Sigma$ must be contained in the Lie triple system

$$\mathcal{C}(v) = \{z \in \mathfrak{p} : [v, z] = 0\},$$

the centralizer of v in \mathfrak{p} . One has that $\mathcal{C}(v)$ coincides with the normal space $\nu_v(K.v)$ of the isotropy orbit. If Σ is **maximal**, then the orbit $K.v$ must be most singular and hence

$$T_p\Sigma \cap \nu_v^\perp$$

is semisimple.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Non-semisimple totally geodesic submanifolds.

The index of a symmetric space

Carlos Olmos

If $\Sigma \subset M = G/K$ is totally geodesic and $p \in \Sigma$, then $T_p\Sigma$ is a Lie triple system of \mathfrak{p} . Assume that Σ is **not semisimple**. Then there exists $0 \neq v \in T_p\Sigma$ such that $[v, T_p\Sigma] = 0$. Therefore $T_p\Sigma$ must be contained in the Lie triple system

$$\mathcal{C}(v) = \{z \in \mathfrak{p} : [v, z] = 0\},$$

the centralizer of v in \mathfrak{p} . One has that $\mathcal{C}(v)$ coincides with the normal space $\nu_v(K.v)$ of the isotropy orbit. If Σ is **maximal**, then the orbit $K.v$ must be most singular and hence

$$T_p\Sigma \cap \nu_v^\perp$$

is semisimple.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Non-semisimple totally geodesic submanifolds.

The index of a symmetric space

Carlos Olmos

If $\Sigma \subset M = G/K$ is totally geodesic and $p \in \Sigma$, then $T_p\Sigma$ is a Lie triple system of \mathfrak{p} . Assume that Σ is **not semisimple**.

Then there exists $0 \neq v \in T_p\Sigma$ such that $[v, T_p\Sigma] = 0$.

Therefore $T_p\Sigma$ must be contained in the Lie triple system

$$\mathcal{C}(v) = \{z \in \mathfrak{p} : [v, z] = 0\},$$

the centralizer of v in \mathfrak{p} . One has that $\mathcal{C}(v)$ coincides with the normal space $\nu_v(K.v)$ of the isotropy orbit. If Σ is **maximal**, then the orbit $K.v$ must be most singular and hence

$$T_p\Sigma \cap \nu_v^\perp$$

is semisimple.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Non-semisimple totally geodesic submanifolds.

The index of a symmetric space

Carlos Olmos

If $\Sigma \subset M = G/K$ is totally geodesic and $p \in \Sigma$, then $T_p\Sigma$ is a Lie triple system of \mathfrak{p} . Assume that Σ is **not semisimple**. Then there exists $0 \neq v \in T_p\Sigma$ such that $[v, T_p\Sigma] = 0$.

Therefore $T_p\Sigma$ must be contained in the Lie triple system

$$\mathcal{C}(v) = \{z \in \mathfrak{p} : [v, z] = 0\},$$

the centralizer of v in \mathfrak{p} . One has that $\mathcal{C}(v)$ coincides with the normal space $\nu_v(K.v)$ of the isotropy orbit. If Σ is **maximal**, then the orbit $K.v$ must be most singular and hence

$$T_p\Sigma \cap \nu_v^\perp$$

is semisimple.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Non-semisimple totally geodesic submanifolds.

The index of a symmetric space

Carlos Olmos

If $\Sigma \subset M = G/K$ is totally geodesic and $p \in \Sigma$, then $T_p\Sigma$ is a Lie triple system of \mathfrak{p} . Assume that Σ is **not semisimple**. Then there exists $0 \neq v \in T_p\Sigma$ such that $[v, T_p\Sigma] = 0$. Therefore $T_p\Sigma$ must be contained in the Lie triple system

$$\mathcal{C}(v) = \{z \in \mathfrak{p} : [v, z] = 0\},$$

the centralizer of v in \mathfrak{p} . One has that $\mathcal{C}(v)$ coincides with the normal space $\nu_v(K.v)$ of the isotropy orbit. If Σ is **maximal**, then the orbit $K.v$ must be most singular and hence

$$T_p\Sigma \cap \nu_v^\perp$$

is semisimple.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Non-semisimple totally geodesic submanifolds.

The index of a symmetric space

Carlos Olmos

If $\Sigma \subset M = G/K$ is totally geodesic and $p \in \Sigma$, then $T_p\Sigma$ is a Lie triple system of \mathfrak{p} . Assume that Σ is **not semisimple**. Then there exists $0 \neq v \in T_p\Sigma$ such that $[v, T_p\Sigma] = 0$. Therefore $T_p\Sigma$ must be contained in the Lie triple system

$$\mathcal{C}(v) = \{z \in \mathfrak{p} : [v, z] = 0\},$$

the centralizer of v in \mathfrak{p} . One has that $\mathcal{C}(v)$ coincides with the normal space $\nu_v(K.v)$ of the isotropy orbit. If Σ is **maximal**, then the orbit $K.v$ must be most singular and hence

$$T_p\Sigma \cap \nu_v^\perp$$

is semisimple.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Non-semisimple totally geodesic submanifolds.

The index of a symmetric space

Carlos Olmos

If $\Sigma \subset M = G/K$ is totally geodesic and $p \in \Sigma$, then $T_p\Sigma$ is a Lie triple system of \mathfrak{p} . Assume that Σ is **not semisimple**. Then there exists $0 \neq v \in T_p\Sigma$ such that $[v, T_p\Sigma] = 0$. Therefore $T_p\Sigma$ must be contained in the Lie triple system

$$\mathcal{C}(v) = \{z \in \mathfrak{p} : [v, z] = 0\},$$

the centralizer of v in \mathfrak{p} . One has that $\mathcal{C}(v)$ coincides with the normal space $\nu_v(K.v)$ of the isotropy orbit. If Σ is **maximal**, then the orbit $K.v$ must be most singular and hence

$$T_p\Sigma \cap \nu_v^\perp$$

is semisimple.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Non-semisimple totally geodesic submanifolds.

The index of a symmetric space

Carlos Olmos

If $\Sigma \subset M = G/K$ is totally geodesic and $p \in \Sigma$, then $T_p\Sigma$ is a Lie triple system of \mathfrak{p} . Assume that Σ is **not semisimple**. Then there exists $0 \neq v \in T_p\Sigma$ such that $[v, T_p\Sigma] = 0$. Therefore $T_p\Sigma$ must be contained in the Lie triple system

$$\mathcal{C}(v) = \{z \in \mathfrak{p} : [v, z] = 0\},$$

the centralizer of v in \mathfrak{p} . One has that $\mathcal{C}(v)$ coincides with the normal space $\nu_v(K.v)$ of the isotropy orbit. If Σ is **maximal**, then the orbit $K.v$ must be most singular and hence

$$T_p\Sigma \cap \nu_v^\perp$$

is semisimple.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

The following result gives a nice characterization of the maximal non-semisimple totally geodesic submanifolds of a symmetric space.

Theorem (Berndt-O.)

Let Σ be a non-semisimple totally geodesic submanifold of a symmetric space $M = G/K$, $p = [e] \in \Sigma$. Then Σ is a maximal totally geodesic submanifold of M if and only if $T_p\Sigma$ coincides with the normal space to an extrinsic symmetric orbit $K.v$ (and so it is reflective).

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

The following result gives a nice characterization of the maximal non-semisimple totally geodesic submanifolds of a symmetric space.

Theorem (Berndt-O.)

Let Σ be a non-semisimple totally geodesic submanifold of a symmetric space $M = G/K$, $p = [e] \in \Sigma$. Then Σ is a maximal totally geodesic submanifold of M if and only if $T_p\Sigma$ coincides with the normal space to an extrinsic symmetric orbit $K.v$ (and so it is reflective).

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

The following result gives a nice characterization of the maximal non-semisimple totally geodesic submanifolds of a symmetric space.

Theorem (Berndt-O.)

Let Σ be a non-semisimple totally geodesic submanifold of a symmetric space $M = G/K$, $p = [e] \in \Sigma$. Then Σ is a maximal totally geodesic submanifold of M if and only if $T_p\Sigma$ coincides with the normal space to an extrinsic symmetric orbit $K.v$ (and so it is reflective).

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

The following result gives a nice characterization of the maximal non-semisimple totally geodesic submanifolds of a symmetric space.

Theorem (Berndt-O.)

Let Σ be a non-semisimple totally geodesic submanifold of a symmetric space $M = G/K$, $p = [e] \in \Sigma$. Then Σ is a maximal totally geodesic submanifold of M if and only if $T_p\Sigma$ coincides with the normal space to an extrinsic symmetric orbit $K.v$ (and so it is reflective).

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

The following result gives a nice characterization of the maximal non-semisimple totally geodesic submanifolds of a symmetric space.

Theorem (Berndt-O.)

Let Σ be a non-semisimple totally geodesic submanifold of a symmetric space $M = G/K$, $p = [e] \in \Sigma$. Then Σ is a maximal totally geodesic submanifold of M if and only if $T_p\Sigma$ coincides with the normal space to an extrinsic symmetric orbit $K.v$ (and so it is reflective).

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Fixed vectors of the slice representation.

The index of a symmetric space

Carlos Olmos

Theorem (Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible, simply connected, Riemannian symmetric space with $\text{rk}(M) \geq 2$, where $G = I(M)^\circ$, $K = G_p$ and $p \in M$. Let $\Sigma = G'/K'$ be a (proper) totally geodesic submanifold of M with $p \in \Sigma$ and $\dim(\Sigma) \geq \frac{1}{2} \dim(M)$, where G' is the subgroup of G consisting of the glide transformations of Σ and $K' = (G')_p$. Let ρ be the slice representation of $(K')^\circ$ on $SO(\nu_o \Sigma)$. Then the following statements are equivalent:

- (i) Σ is maximal and there exists a non-zero vector in $\nu_o \Sigma$ that is fixed by the slice representation ρ .
- (ii) Σ is reflective and the complementary reflective submanifold is non-semisimple.
- (iii) $T_o \Sigma$ coincides, as a linear subspace, with the tangent space $T_v(K \cdot v)$ of a symmetric isotropy orbit.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Fixed vectors of the slice representation.

The index of a symmetric space

Carlos Olmos

Theorem (Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible, simply connected, Riemannian symmetric space with $\text{rk}(M) \geq 2$, where $G = I(M)^\circ$, $K = G_p$ and $p \in M$. Let $\Sigma = G'/K'$ be a (proper) totally geodesic submanifold of M with $p \in \Sigma$ and $\dim(\Sigma) \geq \frac{1}{2} \dim(M)$, where G' is the subgroup of G consisting of the glide transformations of Σ and $K' = (G')_p$. Let ρ be the slice representation of $(K')^\circ$ on $SO(\nu_o \Sigma)$. Then the following statements are equivalent:

- (i) Σ is maximal and there exists a non-zero vector in $\nu_o \Sigma$ that is fixed by the slice representation ρ .
- (ii) Σ is reflective and the complementary reflective submanifold is non-semisimple.
- (iii) $T_o \Sigma$ coincides, as a linear subspace, with the tangent space $T_\nu(K \cdot \nu)$ of a symmetric isotropy orbit.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Fixed vectors of the slice representation.

The index of a symmetric space

Carlos Olmos

Theorem (Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible, simply connected, Riemannian symmetric space with $\text{rk}(M) \geq 2$, where $G = I(M)^\circ$, $K = G_p$ and $p \in M$. Let $\Sigma = G'/K'$ be a (proper) totally geodesic submanifold of M with $p \in \Sigma$ and $\dim(\Sigma) \geq \frac{1}{2} \dim(M)$, where G' is the subgroup of G consisting of the glide transformations of Σ and $K' = (G')_p$. Let ρ be the slice representation of $(K')^\circ$ on $SO(\nu_o \Sigma)$. Then the following statements are equivalent:

- (i) Σ is maximal and there exists a non-zero vector in $\nu_o \Sigma$ that is fixed by the slice representation ρ .
- (ii) Σ is reflective and the complementary reflective submanifold is non-semisimple.
- (iii) $T_o \Sigma$ coincides, as a linear subspace, with the tangent space $T_v(K \cdot v)$ of a symmetric isotropy orbit.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Fixed vectors of the slice representation.

The index of a symmetric space

Carlos Olmos

Theorem (Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible, simply connected, Riemannian symmetric space with $\text{rk}(M) \geq 2$, where $G = I(M)^\circ$, $K = G_p$ and $p \in M$. Let $\Sigma = G'/K'$ be a (proper) totally geodesic submanifold of M with $p \in \Sigma$ and $\dim(\Sigma) \geq \frac{1}{2} \dim(M)$, where G' is the subgroup of G consisting of the glide transformations of Σ and $K' = (G')_p$. Let ρ be the slice representation of $(K')^\circ$ on $SO(\nu_o\Sigma)$. Then the following statements are equivalent:

- (i) Σ is maximal and there exists a non-zero vector in $\nu_o\Sigma$ that is fixed by the slice representation ρ .
- (ii) Σ is reflective and the complementary reflective submanifold is non-semisimple.
- (iii) $T_o\Sigma$ coincides, as a linear subspace, with the tangent space $T_v(K \cdot v)$ of a symmetric isotropy orbit.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Fixed vectors of the slice representation.

The index of a symmetric space

Carlos Olmos

Theorem (Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible, simply connected, Riemannian symmetric space with $\text{rk}(M) \geq 2$, where $G = I(M)^\circ$, $K = G_p$ and $p \in M$. Let $\Sigma = G'/K'$ be a (proper) totally geodesic submanifold of M with $p \in \Sigma$ and $\dim(\Sigma) \geq \frac{1}{2} \dim(M)$, where G' is the subgroup of G consisting of the glide transformations of Σ and $K' = (G')_p$. Let ρ be the slice representation of $(K')^\circ$ on $SO(\nu_o\Sigma)$. Then the following statements are equivalent:

- (i) Σ is maximal and there exists a non-zero vector in $\nu_o\Sigma$ that is fixed by the slice representation ρ .
- (ii) Σ is reflective and the complementary reflective submanifold is non-semisimple.
- (iii) $T_o\Sigma$ coincides, as a linear subspace, with the tangent space $T_\nu(K \cdot \nu)$ of a symmetric isotropy orbit.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Fixed vectors of the slice representation.

The index of a symmetric space

Carlos Olmos

Theorem (Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible, simply connected, Riemannian symmetric space with $\text{rk}(M) \geq 2$, where $G = I(M)^\circ$, $K = G_p$ and $p \in M$. Let $\Sigma = G'/K'$ be a (proper) totally geodesic submanifold of M with $p \in \Sigma$ and $\dim(\Sigma) \geq \frac{1}{2} \dim(M)$, where G' is the subgroup of G consisting of the glide transformations of Σ and $K' = (G')_p$. Let ρ be the slice representation of $(K')^\circ$ on $SO(\nu_o\Sigma)$. Then the following statements are equivalent:

- (i) Σ is maximal and there exists a non-zero vector in $\nu_o\Sigma$ that is fixed by the slice representation ρ .
- (ii) Σ is reflective and the complementary reflective submanifold is non-semisimple.
- (iii) $T_o\Sigma$ coincides, as a linear subspace, with the tangent space $T_v(K \cdot v)$ of a symmetric isotropy orbit.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Fixed vectors of the slice representation.

The index of a symmetric space

Carlos Olmos

Theorem (Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible, simply connected, Riemannian symmetric space with $\text{rk}(M) \geq 2$, where $G = I(M)^\circ$, $K = G_p$ and $p \in M$. Let $\Sigma = G'/K'$ be a (proper) totally geodesic submanifold of M with $p \in \Sigma$ and $\dim(\Sigma) \geq \frac{1}{2} \dim(M)$, where G' is the subgroup of G consisting of the glide transformations of Σ and $K' = (G')_p$. Let ρ be the slice representation of $(K')^\circ$ on $SO(\nu_o\Sigma)$. Then the following statements are equivalent:

- (i) Σ is maximal and there exists a non-zero vector in $\nu_o\Sigma$ that is fixed by the slice representation ρ .
- (ii) Σ is reflective and the complementary reflective submanifold is non-semisimple.
- (iii) $T_o\Sigma$ coincides, as a linear subspace, with the tangent space $T_\nu(K \cdot \nu)$ of a symmetric isotropy orbit.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Fixed vectors of the slice representation.

The index of a symmetric space

Carlos Olmos

Theorem (Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible, simply connected, Riemannian symmetric space with $\text{rk}(M) \geq 2$, where $G = I(M)^\circ$, $K = G_p$ and $p \in M$. Let $\Sigma = G'/K'$ be a (proper) totally geodesic submanifold of M with $p \in \Sigma$ and $\dim(\Sigma) \geq \frac{1}{2} \dim(M)$, where G' is the subgroup of G consisting of the glide transformations of Σ and $K' = (G')_p$. Let ρ be the slice representation of $(K')^\circ$ on $SO(\nu_o\Sigma)$. Then the following statements are equivalent:

- (i) Σ is maximal and there exists a non-zero vector in $\nu_o\Sigma$ that is fixed by the slice representation ρ .
- (ii) Σ is reflective and the complementary reflective submanifold is non-semisimple.
- (iii) $T_o\Sigma$ coincides, as a linear subspace, with the tangent space $T_\nu(K \cdot \nu)$ of a symmetric isotropy orbit.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Fixed vectors of the slice representation.

The index of a symmetric space

Carlos Olmos

Theorem (Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible, simply connected, Riemannian symmetric space with $\text{rk}(M) \geq 2$, where $G = I(M)^\circ$, $K = G_p$ and $p \in M$. Let $\Sigma = G'/K'$ be a (proper) totally geodesic submanifold of M with $p \in \Sigma$ and $\dim(\Sigma) \geq \frac{1}{2} \dim(M)$, where G' is the subgroup of G consisting of the glide transformations of Σ and $K' = (G')_p$. Let ρ be the slice representation of $(K')^\circ$ on $SO(\nu_o\Sigma)$. Then the following statements are equivalent:

- (i) Σ is maximal and there exists a non-zero vector in $\nu_o\Sigma$ that is fixed by the slice representation ρ .
- (ii) Σ is reflective and the complementary reflective submanifold is non-semisimple.
- (iii) $T_o\Sigma$ coincides, as a linear subspace, with the tangent space $T_\nu(K \cdot \nu)$ of a symmetric isotropy orbit.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Fixed vectors of the slice representation.

The index of a symmetric space

Carlos Olmos

Theorem (Berndt-O.-Rodríguez)

Let $M = G/K$ be an irreducible, simply connected, Riemannian symmetric space with $\text{rk}(M) \geq 2$, where $G = I(M)^\circ$, $K = G_p$ and $p \in M$. Let $\Sigma = G'/K'$ be a (proper) totally geodesic submanifold of M with $p \in \Sigma$ and $\dim(\Sigma) \geq \frac{1}{2} \dim(M)$, where G' is the subgroup of G consisting of the glide transformations of Σ and $K' = (G')_p$. Let ρ be the slice representation of $(K')^\circ$ on $SO(\nu_o\Sigma)$. Then the following statements are equivalent:

- (i) Σ is maximal and there exists a non-zero vector in $\nu_o\Sigma$ that is fixed by the slice representation ρ .
- (ii) Σ is reflective and the complementary reflective submanifold is non-semisimple.
- (iii) $T_o\Sigma$ coincides, as a linear subspace, with the tangent space $T_v(K \cdot v)$ of a symmetric isotropy orbit.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

The index conjecture.

Let us define the *reflective index* of a symmetric space M by

$$i_r = \min \{ \text{codim}(\Sigma) : \Sigma \subsetneq M \text{ is totally geodesic and reflective} \}$$

The reflective index can be computed from Leung's classification of reflective totally geodesic submanifolds of symmetric spaces. Clearly, $i(M) \leq i_r(M)$. Therefore

$$\text{rk}(M) \leq i(M) \leq i_r(M)$$

In all known examples $i(M) = i_r(M)$, except for the space $M = G_2^2/\text{SO}_4$, or its compact dual. In this case the index is 3 but the reflective index is 4. We conjecture that this is the only exception. Namely,

Conjecture. *The index of an irreducible symmetric space M , which is different from $G_2/\text{SO}(4)$ and its symmetric dual, coincides with its reflective index $i_r(M)$.*

The index conjecture.

Let us define the *reflective index* of a symmetric space M by

$$i_r = \min \{ \text{codim}(\Sigma) : \Sigma \subsetneq M \text{ is totally geodesic and reflective} \}$$

The reflective index can be computed from Leung's classification of reflective totally geodesic submanifolds of symmetric spaces. Clearly, $i(M) \leq i_r(M)$. Therefore

$$\text{rk}(M) \leq i(M) \leq i_r(M)$$

In all known examples $i(M) = i_r(M)$, except for the space $M = G_2^2/\text{SO}_4$, or its compact dual. In this case the index is 3 but the reflective index is 4. We conjecture that this is the only exception. Namely,

Conjecture. *The index of an irreducible symmetric space M , which is different from $G_2/\text{SO}(4)$ and its symmetric dual, coincides with its reflective index $i_r(M)$.*

The index conjecture.

Let us define the *reflective index* of a symmetric space M by

$$i_r = \min \{ \text{codim}(\Sigma) : \Sigma \subsetneq M \text{ is totally geodesic and reflective} \}$$

The reflective index can be computed from Leung's classification of reflective totally geodesic submanifolds of symmetric spaces. Clearly, $i(M) \leq i_r(M)$. Therefore

$$\text{rk}(M) \leq i(M) \leq i_r(M)$$

In all known examples $i(M) = i_r(M)$, except for the space $M = G_2^2/\text{SO}_4$, or its compact dual. In this case the index is 3 but the reflective index is 4. We conjecture that this is the only exception. Namely,

Conjecture. *The index of an irreducible symmetric space M , which is different from $G_2/\text{SO}(4)$ and its symmetric dual, coincides with its reflective index $i_r(M)$.*

The index conjecture.

Let us define the *reflective index* of a symmetric space M by

$$i_r = \min \{ \text{codim}(\Sigma) : \Sigma \subsetneq M \text{ is totally geodesic and reflective} \}$$

The reflective index can be computed from Leung's classification of reflective totally geodesic submanifolds of symmetric spaces. Clearly, $i(M) \leq i_r(M)$. Therefore

$$\text{rk}(M) \leq i(M) \leq i_r(M)$$

In all known examples $i(M) = i_r(M)$, except for the space $M = G_2/SO_4$, or its compact dual. In this case the index is 3 but the reflective index is 4. We conjecture that this is the only exception. Namely,

Conjecture. *The index of an irreducible symmetric space M , which is different from $G_2/SO(4)$ and its symmetric dual, coincides with its reflective index $i_r(M)$.*

The index conjecture.

Let us define the *reflective index* of a symmetric space M by

$$i_r = \min \{ \text{codim}(\Sigma) : \Sigma \subsetneq M \text{ is totally geodesic and reflective} \}$$

The reflective index can be computed from Leung's classification of reflective totally geodesic submanifolds of symmetric spaces. Clearly, $i(M) \leq i_r(M)$. Therefore

$$\text{rk}(M) \leq i(M) \leq i_r(M)$$

In all known examples $i(M) = i_r(M)$, except for the space $M = G_2^2/\text{SO}_4$, or its compact dual. In this case the index is 3 but the reflective index is 4. We conjecture that this is the only exception. Namely,

Conjecture. *The index of an irreducible symmetric space M , which is different from $G_2/\text{SO}(4)$ and its symmetric dual, coincides with its reflective index $i_r(M)$.*

The index conjecture.

Let us define the *reflective index* of a symmetric space M by

$$i_r = \min \{ \text{codim}(\Sigma) : \Sigma \subsetneq M \text{ is totally geodesic and reflective} \}$$

The reflective index can be computed from Leung's classification of reflective totally geodesic submanifolds of symmetric spaces. Clearly, $i(M) \leq i_r(M)$. Therefore

$$\text{rk}(M) \leq i(M) \leq i_r(M)$$

In all known examples $i(M) = i_r(M)$, except for the space $M = G_2^2/\text{SO}_4$, or its compact dual. In this case the index is 3 but the reflective index is 4. We conjecture that this is the only exception. Namely,

Conjecture. *The index of an irreducible symmetric space M , which is different from $G_2/\text{SO}(4)$ and its symmetric dual, coincides with its reflective index $i_r(M)$.*

The index conjecture.

Let us define the *reflective index* of a symmetric space M by

$$i_r = \min \{ \text{codim}(\Sigma) : \Sigma \subsetneq M \text{ is totally geodesic and reflective} \}$$

The reflective index can be computed from Leung's classification of reflective totally geodesic submanifolds of symmetric spaces. Clearly, $i(M) \leq i_r(M)$. Therefore

$$\text{rk}(M) \leq i(M) \leq i_r(M)$$

In all known examples $i(M) = i_r(M)$, except for the space $M = G_2/SO_4$, or its compact dual. In this case the index is 3 but the reflective index is 4. We conjecture that this is the only exception. Namely,

Conjecture. *The index of an irreducible symmetric space M , which is different from $G_2/SO(4)$ and its symmetric dual, coincides with its reflective index $i_r(M)$.*

The index conjecture.

Let us define the *reflective index* of a symmetric space M by

$$i_r = \min \{ \text{codim}(\Sigma) : \Sigma \subsetneq M \text{ is totally geodesic and reflective} \}$$

The reflective index can be computed from Leung's classification of reflective totally geodesic submanifolds of symmetric spaces. Clearly, $i(M) \leq i_r(M)$. Therefore

$$\text{rk}(M) \leq i(M) \leq i_r(M)$$

In all known examples $i(M) = i_r(M)$, **except for the space $M = G_2^2/\text{SO}_4$** , or its compact dual. In this case the index is 3 but the reflective index is 4. We conjecture that this is the only exception. Namely,

Conjecture. *The index of an irreducible symmetric space M , which is different from $G_2/\text{SO}(4)$ and its symmetric dual, coincides with its reflective index $i_r(M)$.*

The index conjecture.

Let us define the *reflective index* of a symmetric space M by

$$i_r = \min \{ \text{codim}(\Sigma) : \Sigma \subsetneq M \text{ is totally geodesic and reflective} \}$$

The reflective index can be computed from Leung's classification of reflective totally geodesic submanifolds of symmetric spaces. Clearly, $i(M) \leq i_r(M)$. Therefore

$$\text{rk}(M) \leq i(M) \leq i_r(M)$$

In all known examples $i(M) = i_r(M)$, **except for the space $M = G_2^2/\text{SO}_4$** , or its compact dual. In this case the index is 3 but the reflective index is 4. We conjecture that this is the only exception. Namely,

Conjecture. *The index of an irreducible symmetric space M , which is different from $G_2/\text{SO}(4)$ and its symmetric dual, coincides with its reflective index $i_r(M)$.*

The index conjecture.

Let us define the *reflective index* of a symmetric space M by

$$i_r = \min \{ \text{codim}(\Sigma) : \Sigma \subsetneq M \text{ is totally geodesic and reflective} \}$$

The reflective index can be computed from Leung's classification of reflective totally geodesic submanifolds of symmetric spaces. Clearly, $i(M) \leq i_r(M)$. Therefore

$$\text{rk}(M) \leq i(M) \leq i_r(M)$$

In all known examples $i(M) = i_r(M)$, **except for the space $M = G_2^2/\text{SO}_4$** , or its compact dual. In this case the index is 3 but the reflective index is 4. We conjecture that this is the only exception. Namely,

Conjecture. *The index of an irreducible symmetric space M , which is different from $G_2/\text{SO}(4)$ and its symmetric dual, coincides with its reflective index $i_r(M)$.*

The index conjecture.

Let us define the *reflective index* of a symmetric space M by

$$i_r = \min \{ \text{codim}(\Sigma) : \Sigma \subsetneq M \text{ is totally geodesic and reflective} \}$$

The reflective index can be computed from Leung's classification of reflective totally geodesic submanifolds of symmetric spaces. Clearly, $i(M) \leq i_r(M)$. Therefore

$$\text{rk}(M) \leq i(M) \leq i_r(M)$$

In all known examples $i(M) = i_r(M)$, **except for the space $M = G_2/SO_4$** , or its compact dual. In this case the index is 3 but the reflective index is 4. We conjecture that this is the only exception. Namely,

Conjecture. *The index of an irreducible symmetric space M , which is different from $G_2/SO(4)$ and its symmetric dual, coincides with its reflective index $i_r(M)$.*

We proved this conjecture for many classical families and for all symmetric spaces of group type. Moreover, we also determined the index, verifying the conjecture, for all exceptional symmetric spaces.

The conjecture remains open only for the following three series of classical symmetric spaces and their symmetric dual spaces:

- (i) $M = SO_{2k+2}/U_{k+1}$ for $k \geq 5$. Conjecture: $i(M) = 2k$.
- (ii) $M = SU_{2k+2}/Sp_{k+1}$ for $k \geq 3$. Conjecture: $i(M) = 4k$.
- (iii) $M = Sp_{2k+1}/Sp_k Sp_{k+1}$ for $l \geq 0$ and $k \geq \max\{3, l+2\}$. Conjecture: $i(M) = 4k$.

We have some strategy, for dealing with these families, that hopefully would prove the index conjecture. But this is still a work in progress.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

We proved this conjecture for many classical families and for all symmetric spaces of group type. Moreover, we also determined the index, verifying the conjecture, for all exceptional symmetric spaces.

The conjecture remains open only for the following three series of classical symmetric spaces and their symmetric dual spaces:

- (i) $M = SO_{2k+2}/U_{k+1}$ for $k \geq 5$. Conjecture: $i(M) = 2k$.
- (ii) $M = SU_{2k+2}/Sp_{k+1}$ for $k \geq 3$. Conjecture: $i(M) = 4k$.
- (iii) $M = Sp_{2k+1}/Sp_k Sp_{k+1}$ for $l \geq 0$ and $k \geq \max\{3, l + 2\}$. Conjecture: $i(M) = 4k$.

We have some strategy, for dealing with these families, that hopefully would prove the index conjecture. But this is still a work in progress.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

We proved this conjecture for many classical families and for all symmetric spaces of group type. Moreover, we also determined the index, verifying the conjecture, for all exceptional symmetric spaces.

The conjecture remains open only for the following three series of classical symmetric spaces and their symmetric dual spaces:

- (i) $M = SO_{2k+2}/U_{k+1}$ for $k \geq 5$. Conjecture: $i(M) = 2k$.
- (ii) $M = SU_{2k+2}/Sp_{k+1}$ for $k \geq 3$. Conjecture: $i(M) = 4k$.
- (iii) $M = Sp_{2k+1}/Sp_k Sp_{k+1}$ for $l \geq 0$ and $k \geq \max\{3, l + 2\}$. Conjecture: $i(M) = 4k$.

We have some strategy, for dealing with these families, that hopefully would prove the index conjecture. But this is still a work in progress.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

We proved this conjecture for many classical families and for all symmetric spaces of group type. Moreover, we also determined the index, verifying the conjecture, for all exceptional symmetric spaces.

The conjecture remains open only for the following three series of classical symmetric spaces and their symmetric dual spaces:

(i) $M = SO_{2k+2}/U_{k+1}$ for $k \geq 5$. Conjecture: $i(M) = 2k$.

(ii) $M = SU_{2k+2}/Sp_{k+1}$ for $k \geq 3$. Conjecture: $i(M) = 4k$.

(iii) $M = Sp_{2k+1}/Sp_k Sp_{k+1}$ for $l \geq 0$ and $k \geq \max\{3, l+2\}$.
Conjecture: $i(M) = 4k$.

We have some strategy, for dealing with these families, that hopefully would prove the index conjecture. But this is still a work in progress.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

We proved this conjecture for many classical families and for all symmetric spaces of group type. Moreover, we also determined the index, verifying the conjecture, for all exceptional symmetric spaces.

The conjecture remains open only for the following three series of classical symmetric spaces and their symmetric dual spaces:

(i) $M = SO_{2k+2}/U_{k+1}$ for $k \geq 5$. Conjecture: $i(M) = 2k$.

(ii) $M = SU_{2k+2}/Sp_{k+1}$ for $k \geq 3$. Conjecture: $i(M) = 4k$.

(iii) $M = Sp_{2k+1}/Sp_k Sp_{k+1}$ for $l \geq 0$ and $k \geq \max\{3, l+2\}$.
Conjecture: $i(M) = 4k$.

We have some strategy, for dealing with these families, that hopefully would prove the index conjecture. But this is still a work in progress.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

We proved this conjecture for many classical families and for all symmetric spaces of group type. Moreover, we also determined the index, verifying the conjecture, for all exceptional symmetric spaces.

The conjecture remains open only for the following three series of classical symmetric spaces and their symmetric dual spaces:

(i) $M = SO_{2k+2}/U_{k+1}$ for $k \geq 5$. Conjecture: $i(M) = 2k$.

(ii) $M = SU_{2k+2}/Sp_{k+1}$ for $k \geq 3$. Conjecture: $i(M) = 4k$.

(iii) $M = Sp_{2k+1}/Sp_k Sp_{k+1}$ for $l \geq 0$ and $k \geq \max\{3, l+2\}$.
Conjecture: $i(M) = 4k$.

We have some strategy, for dealing with these families, that hopefully would prove the index conjecture. But this is still a work in progress.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

We proved this conjecture for many classical families and for all symmetric spaces of group type. Moreover, we also determined the index, verifying the conjecture, for all exceptional symmetric spaces.

The conjecture remains open only for the following three series of classical symmetric spaces and their symmetric dual spaces:

- (i) $M = SO_{2k+2}/U_{k+1}$ for $k \geq 5$. Conjecture: $i(M) = 2k$.
- (ii) $M = SU_{2k+2}/Sp_{k+1}$ for $k \geq 3$. Conjecture: $i(M) = 4k$.
- (iii) $M = Sp_{2k+1}/Sp_k Sp_{k+1}$ for $l \geq 0$ and $k \geq \max\{3, l + 2\}$. Conjecture: $i(M) = 4k$.

We have some strategy, for dealing with these families, that hopefully would prove the index conjecture. But this is still a work in progress.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

We proved this conjecture for many classical families and for all symmetric spaces of group type. Moreover, we also determined the index, verifying the conjecture, for all exceptional symmetric spaces.

The conjecture remains open only for the following three series of classical symmetric spaces and their symmetric dual spaces:

- (i) $M = SO_{2k+2}/U_{k+1}$ for $k \geq 5$. Conjecture: $i(M) = 2k$.
- (ii) $M = SU_{2k+2}/Sp_{k+1}$ for $k \geq 3$. Conjecture: $i(M) = 4k$.
- (iii) $M = Sp_{2k+1}/Sp_k Sp_{k+1}$ for $l \geq 0$ and $k \geq \max\{3, l + 2\}$. Conjecture: $i(M) = 4k$.

We have some strategy, for dealing with these families, that hopefully would prove the index conjecture. But this is still a work in progress.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

We proved this conjecture for many classical families and for all symmetric spaces of group type. Moreover, we also determined the index, verifying the conjecture, for all exceptional symmetric spaces.

The conjecture remains open only for the following three series of classical symmetric spaces and their symmetric dual spaces:

- (i) $M = SO_{2k+2}/U_{k+1}$ for $k \geq 5$. Conjecture: $i(M) = 2k$.
- (ii) $M = SU_{2k+2}/Sp_{k+1}$ for $k \geq 3$. Conjecture: $i(M) = 4k$.
- (iii) $M = Sp_{2k+1}/Sp_k Sp_{k+1}$ for $l \geq 0$ and $k \geq \max\{3, l + 2\}$. Conjecture: $i(M) = 4k$.

We have some strategy, for dealing with these families, that hopefully would prove the index conjecture. But this is still a work in progress.

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.









Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

References

-  Berndt, J., Olmos, C., *On the index of symmetry*, J. reine angew. Math. **737** (2018), 33–48.
-  Berndt, J., Olmos, C., *Maximal totally geodesic submanifolds and index of symmetric spaces*, J. Differential Geometry **104** (2016), 187-217.
-  Berndt, J., Olmos, C., *The index of compact simple Lie groups*, Bull. London Math. Soc. **49** (2017), 903-907.
-  Berndt, J., Olmos, C., Rodríguez, J.S., *The index of exceptional symmetric spaces*, (2019), arXiv:1905.06250.
-  Berndt, J., Tamaru, H., *Cohomogeneity one actions on noncompact symmetric spaces with a totally geodesic singular orbit*, Tohoku Math. J. **56** (2004), 16–177.
-  Klein, Sebastian, a (*converging*) sequence of papers.
-  Leung, D.S.P, a sequence of papers.
-  Nagano + Nagano-Tanaka, a sequence of papers.

The index of a symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of Simons holonomy theorem.

Reflective totally geodesic submanifolds.

Sufficient criteria for reflectivity.

Non-semisimple totally geodesic submanifolds.

Fixed vectors of the slice representation.

The index conjecture.

References

Introduction.

Rank and index.

Applications of
Simons holonomy
theorem.

Reflective totally
geodesic
submanifolds.

Sufficient criteria
for reflectivity.

Non-semisimple totally
geodesic submanifolds.

Fixed vectors of the slice
representation.

The index
conjecture.

References

Happy birthday Jürgen!!

*Thank you for the generous and great influence of your
ideas and work!*

Moitas grazas pola atención e
gocen da gran hospitalidade
galega!!

The index of a
symmetric space

Carlos Olmos

Introduction.

Rank and index.

Applications of
Simons holonomy
theorem.

Reflective totally
geodesic
submanifolds.

Sufficient criteria
for reflectivity.

Non-semisimple totally
geodesic submanifolds.

Fixed vectors of the slice
representation.

The index
conjecture.

References